

# User's Manual

## PMM EP600

ELECTRIC FIELD PROBE

100 kHz ÷ 9.25 GHz

## PMM EP601

ELECTRIC FIELD PROBE

10 kHz ÷ 9.25 GHz

## PMM EP602

ELECTRIC FIELD PROBE

5 kHz ÷ 9.25 GHz

## PMM EP603

ELECTRIC FIELD PROBE

300 kHz ÷ 18 GHz

### SERIAL NUMBER OF THE INSTRUMENT

You can find the Serial Number on the fiber optic holder of the instrument.

The Serial Number is in the form: 000XY00000.

The first three digits and the two letters are the Serial Number prefix, the last five digits are the Serial Number suffix. The prefix is the same for identical instruments, it changes only when a configuration change is made to the instrument.

The suffix is different for each instrument

## NOTE:

® Names and Logo are registered trademarks of Narda Safety Test Solutions GmbH and L3 Communications Holdings, Inc. – Trade names are trademarks of the owners.

If the instrument is used in any other way than as described in this Users Manual, it may become unsafe

Before using this product, the related documentation must be read with great care and fully understood to familiarize with all the safety prescriptions.



To ensure the correct use and the maximum safety level, the User shall know all the instructions and recommendations contained in this document.

This product is a **Safety Class III** instrument according to IEC classification and has been designed to meet the requirements of EN61010-1 (Safety Requirements for Electrical Equipment for Measurement, Control and Laboratory Use).


In accordance with the IEC classification, the battery charger of this product meets requirements **Safety Class II** and **Installation Category II** (having double insulation and able to carry out mono-phase power supply operations)..



It complies with the requirements of **Pollution Class II** (usually only non-conductive pollution). However, occasionally it may become temporarily conductive due to condense on it.

The information contained in this document is subject to change without notice.

## KEY TO THE ELECTRIC AND SAFETY SYMBOLS:

 You now own a high-quality instrument that will give you many years of reliable service. Nevertheless, even this product will eventually become obsolete. When that time comes, please remember that electronic equipment must be disposed of in accordance with local regulations. This product conforms to the WEEE Directive of the European Union (2002/96/EC) and belongs to Category 9 (Monitoring and Control Instruments). You can return the instrument to us free of charge for proper environment friendly disposal. You can obtain further information from your local Narda Sales Partner or by visiting our website at [www.narda-sts.it](http://www.narda-sts.it).



Warning, danger of electric shock



Earth



Read carefully the Operating Manual and its instructions, pay attention to the safety symbols.



Unit Earth Connection



Earth Protection



Equipotential

## KEY TO THE SYMBOLS USED IN THIS DOCUMENT:



**DANGER**

The DANGER sign draws attention to a potential risk to a person's safety. All the precautions must be fully understood and applied before proceeding.



**WARNING**

The WARNING sign draws attention to a potential risk of damage to the apparatus or loss of data. All the precautions must be fully understood and applied before proceeding.



**CAUTION**

The CAUTION sign draws attention against unsafe practices for the apparatus functionality.



**NOTE:**

The NOTE draw attention to important information.

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## **SAFETY RECOMMENDATIONS AND INSTRUCTIONS**

This product has been designed, produced and tested in Italy, and it left the factory in conditions fully complying with the current safety standards. To maintain it in safe conditions and ensure correct use, these general instructions must be fully understood and applied before the product is used.

- When the device must be connected permanently, first provide effective grounding;
- If the device must be connected to other equipment or accessories, make sure they are all safely grounded;
- In case of devices permanently connected to the power supply, and lacking any fuses or other devices of mains protection, the power line must be equipped with adequate protection commensurate to the consumption of all the devices connected to it;
- In case of connection of the device to the power mains, make sure before connection that the voltage selected on the voltage switch and the fuses are adequate for the voltage of the actual mains;
- Devices in Safety Class I, equipped with connection to the power mains by means of cord and plug, can only be plugged into a socket equipped with a ground wire;
- Any interruption or loosening of the ground wire or of a connecting power cable, inside or outside the device, will cause a potential risk for the safety of the personnel;
- Ground connections must not be interrupted intentionally;
- To prevent the possible danger of electrocution, do not remove any covers, panels or guards installed on the device, and refer only to NARDA Service Centers if maintenance should be necessary;
- To maintain adequate protection from fire hazards, replace fuses only with others of the same type and rating;
- Follow the safety regulations and any additional instructions in this manual to prevent accidents and damages.

## EC Conformity Certificate

(in accordance with the Directives: EMC 89/336/EEC and Low Voltage 73/23/EEC)

This is to certify that the product: EP600 Electric field Probe

Produced by: NARDA Safety Test Solutions  
Via Benessea 29/B  
17035 Cisano sul Neva (SV) – ITALY

complies with the following European Standards:

Safety: CEI EN 61010-1 (2001)

EMC: EN 61326-1 (2007)

This product complies with the requirements of the Low Voltage Directive 73/23/EEC, amended by 93/68/EEC, and with the EMC Directive EMC 89/336/EEC amended by 92/31/EEC, 93/68/EEC, 93/97/EEC.

NARDA Safety Test Solutions

## EC Conformity Certificate

(in accordance with the Directives: EMC 89/336/EEC and Low Voltage 73/23/EEC)

This is to certify that the product: EP601 Electric field Probe

Produced by: NARDA Safety Test Solutions  
Via Benessea 29/B  
17035 Cisano sul Neva (SV) – ITALY

complies with the following European Standards:

Safety: CEI EN 61010-1 (2001)

EMC: EN 61326-1 (2007)

This product complies with the requirements of the Low Voltage Directive 73/23/EEC, amended by 93/68/EEC, and with the EMC Directive EMC 89/336/EEC amended by 92/31/EEC, 93/68/EEC, 93/97/EEC.

NARDA Safety Test Solutions

## EC Conformity Certificate

(in accordance with the Directives: EMC 89/336/EEC and Low Voltage 73/23/EEC)

This is to certify that the product: EP602 Electric field Probe

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17035 Cisano sul Neva (SV) – ITALY

complies with the following European Standards:

Safety: CEI EN 61010-1 (2001)

EMC: EN 61326-1 (2007)

This product complies with the requirements of the Low Voltage Directive 73/23/EEC, amended by 93/68/EEC, and with the EMC Directive EMC 89/336/EEC amended by 92/31/EEC, 93/68/EEC, 93/97/EEC.

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## EC Conformity Certificate

(in accordance with the Directives: EMC 89/336/EEC and Low Voltage 73/23/EEC)

This is to certify that the product: EP603 Electric field Probe

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17035 Cisano sul Neva (SV) – ITALY

complies with the following European Standards:

Safety: CEI EN 61010-1 (2001)

EMC: EN 61326-1 (2007)

This product complies with the requirements of the Low Voltage Directive 73/23/EEC, amended by 93/68/EEC, and with the EMC Directive EMC 89/336/EEC amended by 92/31/EEC, 93/68/EEC, 93/97/EEC.

NARDA Safety Test Solutions

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Safety Consideration

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# 1 – General

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## 1.1 Documentation

This Manual includes:

- Questionnaire to resend together with the instrument to service.
- Check list of supplied accessories.

## 1.2 Diode-based isotropic electric field probes

This type of probes are made by small antennas terminated on multiple diodes. To ensure optimal isotropy, the antenna elements are configured orthogonally in order to add all of the electromagnetic wave components. They measure the field independently from field polarization and direction.

The diodes feature linear and quadratic responses to level variations.

At low levels of field the output voltages are proportional to the square value of the field ( $E^2$ ) i.e. to the RMS value.

At higher field levels, up to the saturation, the response becomes linear, thus the output voltages are proportional to the peak value of the field.

The calibration is performed in terms of RMS value in both cases, therefore modulated sources may require a proper correction factor to be taken into account.

### 1.3 Introduction

The EP600/EP601/EP602/EP603 is a diode-type, three-axis technology-edge isotropic sensor of electric fields: from 0.14 to 140 V/m in the frequency range 100 kHz - 9.25 GHz (EP600), from 0.5 to 500 V/m in the frequency range 10 kHz - 9.25 GHz (EP601), from 1.5 to 1500 V/m in the frequency range 5 kHz - 9.25 GHz (EP602) and from 0.17 to 170 V/m in the frequency range 300 kHz - 18 GHz (EP603).

The spherical plastic housing includes: 6 orthogonal cones (one for each monopole) that allow for an easy identification of the electric field vectors; the ON/OFF button and LED; the battery and the charger connector.

A plastic fiber optic (not removable) is fixed to the EP600/EP601/EP602/EP603 housing; at its extremity two connectors compatible with PMM devices allow for connection to PC (via optical adapter) or to the hand-held meter PMM 8053B to display the measurements and to set the proper filter for optimizing noise reduction, sampling time and battery autonomy.

The software supplied allows for storing the measurements and convert the same in text format. The recorded data can be viewed either as a graph or as a table.

The EP600/EP601/EP602/EP603 includes an E<sup>2</sup>PROM that stores serial number, calibration data, calibration factors and Firmware version.

Three Analog/Digital converters – one for each axis - read the electric field simultaneously; the sensors consist in 6 monopoles mounted orthogonally. Another Analog/Digital converter internal to the microcontroller provides the battery voltage and temperature measurements.

The EP600/EP601/EP602/EP603 is supplied by an internal rechargeable battery capable of up to 80 hours of operation.



Fig. 1-1 EP600/EP601/EP602/EP603

#### 1.4 Specifications EP600

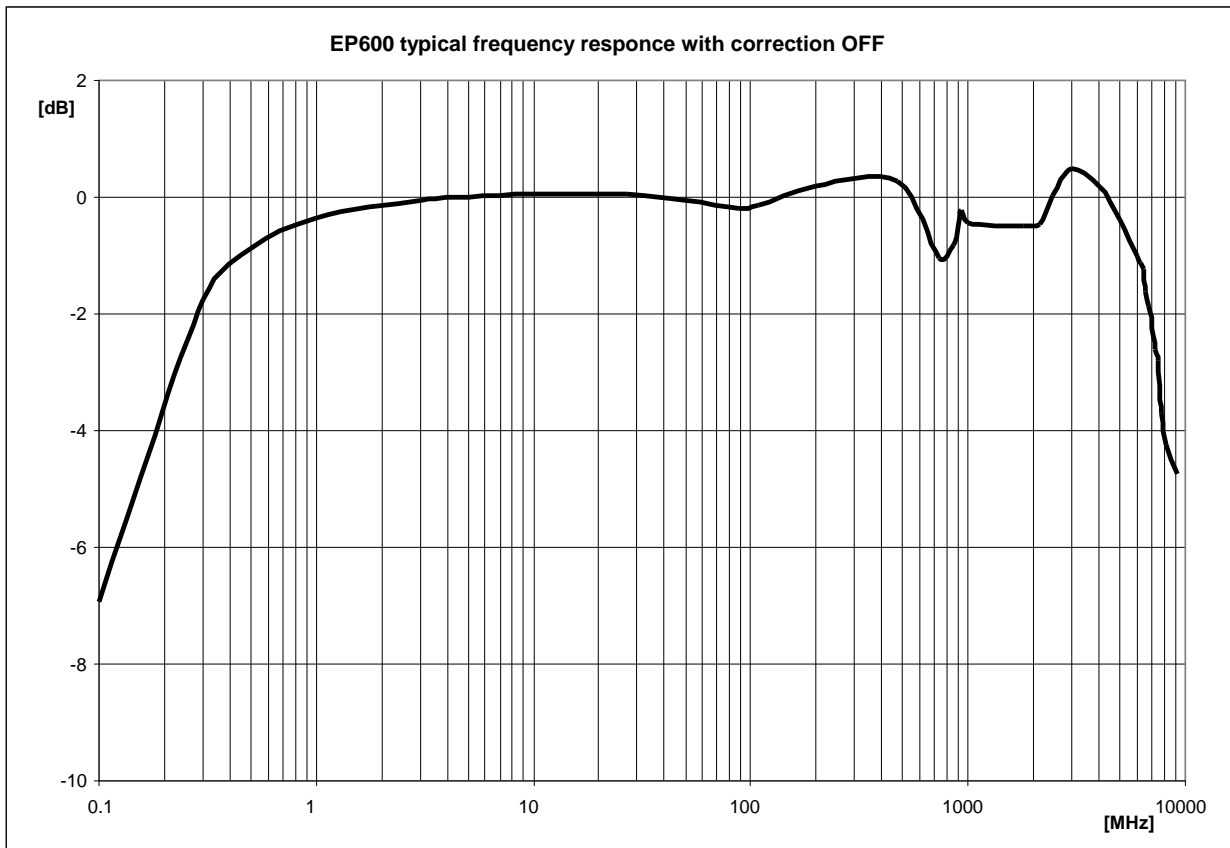
This condition applies to all specifications:

- The operating ambient temperature range must be -10° to 50 °C.

**TABLE 1-1 Specifications of the electric field probe PMM EP600**

Frequency range	100 kHz – 9.25 GHz
Level range	0.14 – 140 V/m
Overload	> 300 V/m
Dynamic range	60 dB
Linearity	0.4 dB @ 50 MHz/0.3 – 100 V/m
Resolution	0.01 V/m
Sensitivity	0.14 V/m
Flatness	1 – 150 MHz 0.8dB 0.5 – 6000 MHz 1.6 dB 0.3 – 7500 MHz 3.2 dB (With frequency correction OFF)  0.3 – 7500 MHz 0.4 dB (Typical with frequency correction ON)
Isotropy	0.5 dB (0.3 dB typical @ 50 MHz)
Sensors	Six monopoles
X/Y/Z reading	Simultaneous sampling of the components
Battery reading	10 mV res.
Temperature reading	0.1 °C res.
Internal data memory	Serial number Date calibration Calibration Factor SW release.
Battery	Panasonic ML621S 3V 5mA/h rechargeable Li-Mn
Operation time	80 h @ 0.4 S/sec 28 Hz filter 60 h @ 5 S/sec 28 Hz filter
Recharge time	48h for maximum autonomy
Dimensions	17 mm sphere 17 mm sensor 53 mm overall
Weight	23g including FO weight (1m)
Operating temperature	-10° - +50°
Software for PC	YES
Optical fiber connector	HFBR-0500
Tripod adapter	¼ - 20 UNC female

# 1.5 Typical frequency response with correction OFF EP600



**Fig. 1-2** EP600 typical frequency response with correction OFF

## 1.6 Specifications EP601

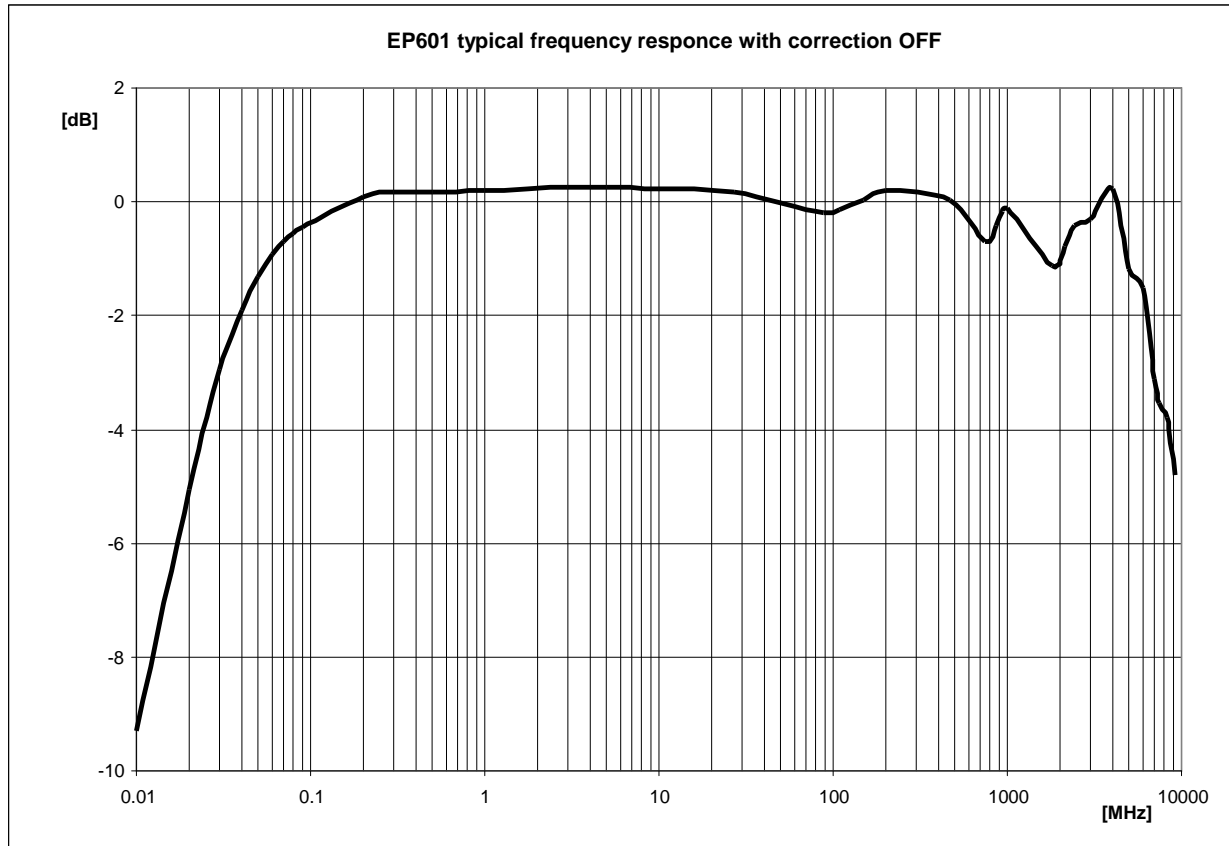
This condition applies to all specifications:

- The operating ambient temperature range must be -10° to 50 °C.

**TABLE 1-2 Specifications of the electric field probe PMM EP601**

Frequency range	10 kHz – 9.25 GHz
Level range	0.5 – 500 V/m
Overload	> 1000 V/m
Dynamic range	60 dB
Linearity	0.4 dB @ 50 MHz/1 – 500 V/m
Resolution	0.01 V/m
Sensitivity	0.5 V/m
Flatness	0.1 – 150 MHz 0.4dB 0.05 – 6000 MHz 1.6 dB 0.03 – 7500 MHz 3.2 dB (With frequency correction OFF)  0.05 – 7500 MHz 0.4 dB (Typical with frequency correction ON)
Isotropy	0.5 dB (0.3 dB typical @ 50 MHz)
Sensors	Six monopoles
X/Y/Z reading	Simultaneous sampling of the components
Battery reading	10 mV res.
Temperature reading	0.1 °C res.
Internal data memory	Serial number Date calibration Calibration Factor SW release.
Battery	Panasonic ML621S 3V 5mA/h rechargeable Li-Mn
Operation time	80 h @ 0.4 S/sec 28 Hz filter 60 h @ 5 S/sec 28 Hz filter
Recharge time	48h for maximum autonomy
Dimensions	17 mm sphere 17 mm sensor 53 mm overall
Weight	23g including FO weight (1m)
Operating temperature	-10° - +50°
Software for PC	YES
Optical fiber connector	HFBR-0500
Tripod adapter	¼ - 20 UNC female

**1.7 Typical  
frequency response  
with correction OFF  
EP601**



**Fig. 1-3 EP601 typical frequency response with correction OFF**

## 1.8 Specifications EP602

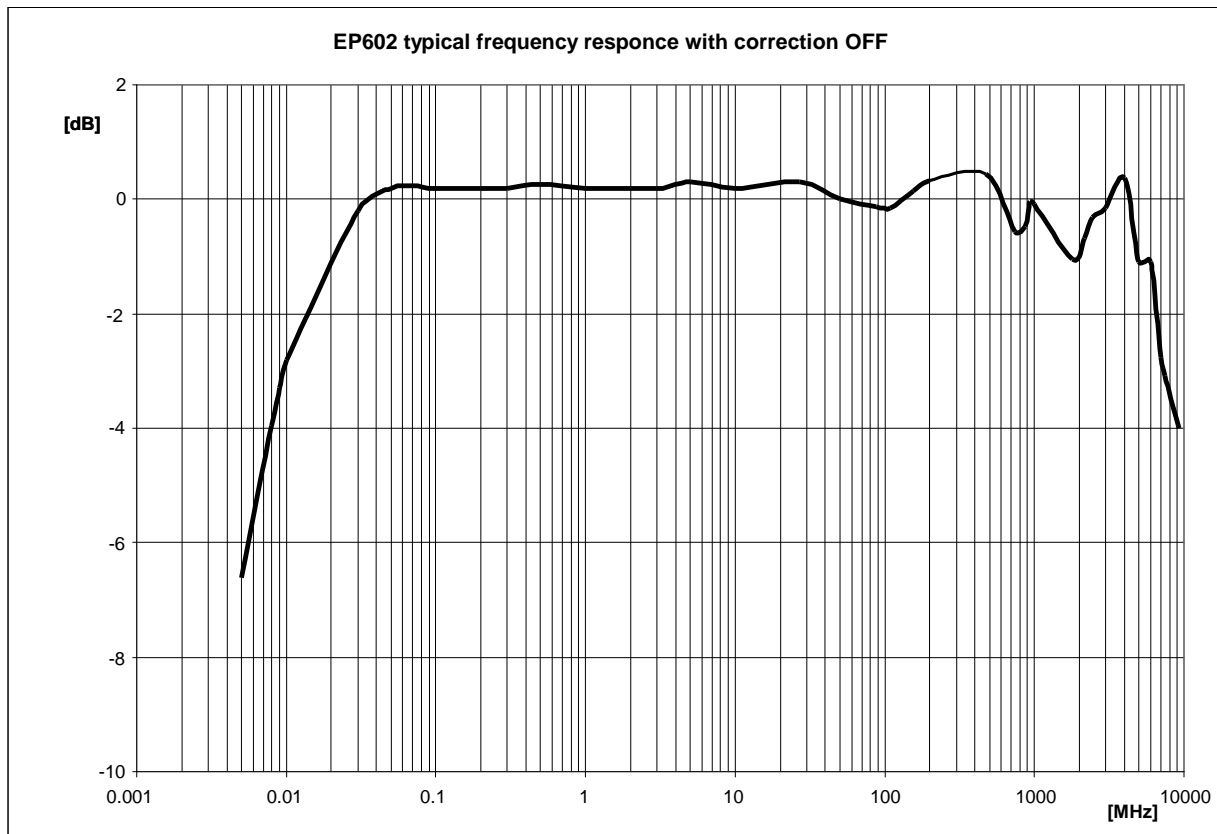
This condition applies to all specifications:

- The operating ambient temperature range must be -10° to 50 °C.

**TABLE 1-3 Specifications of the electric field probe PMM EP602**

Frequency range	5 kHz – 9.25 GHz
Level range	1.5 – 1500 V/m
Overload	> 3000 V/m
Dynamic range	60 dB
Linearity	0.4 dB @ 50 MHz/2.5 – 1000 V/m
Resolution	0.01 V/m
Sensitivity	1.5 V/m
Flatness	0.05 – 150 MHz 0.4dB 0.05 – 6000 MHz 1.6 dB 0.03 – 7500 MHz 3.2 dB (With frequency correction OFF)  0.05 – 7500 MHz 0.4 dB (Typical with frequency correction ON)
Isotropy	0.5 dB (0.3 dB typical @ 50 MHz)
Sensors	Six monopoles
X/Y/Z reading	Simultaneous sampling of the components
Battery reading	10 mV res.
Temperature reading	0.1 °C res.
Internal data memory	Serial number Date calibration Calibration Factor SW release.
Battery	Panasonic ML621S 3V 5mA/h rechargeable Li-Mn
Operation time	80 h @ 0.4 S/sec 28 Hz filter 60 h @ 5 S/sec 28 Hz filter
Recharge time	48h for maximum autonomy
Dimensions	17 mm sphere 17 mm sensor 53 mm overall
Weight	23g including FO weight (1m)
Operating temperature	-10° - +50°
Software for PC	YES
Optical fiber connector	HFBR-0500
Tripod adapter	¼ - 20 UNC female

**1.9 Typical  
frequency response  
with correction OFF  
EP602**



**Fig. 1-4 EP602 typical frequency response with correction OFF**

### 1.10 Specifications EP603

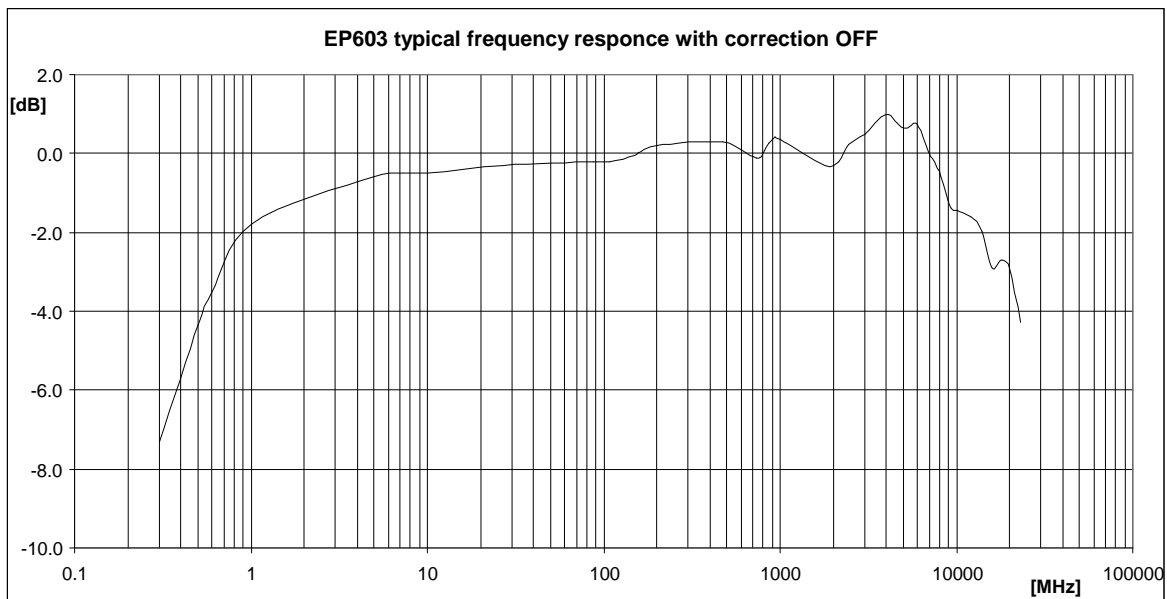
This condition applies to all specifications:

- The operating ambient temperature range must be -10° to 50 °C.

**TABLE 1-4 Specifications of the electric field probe PMM EP603**

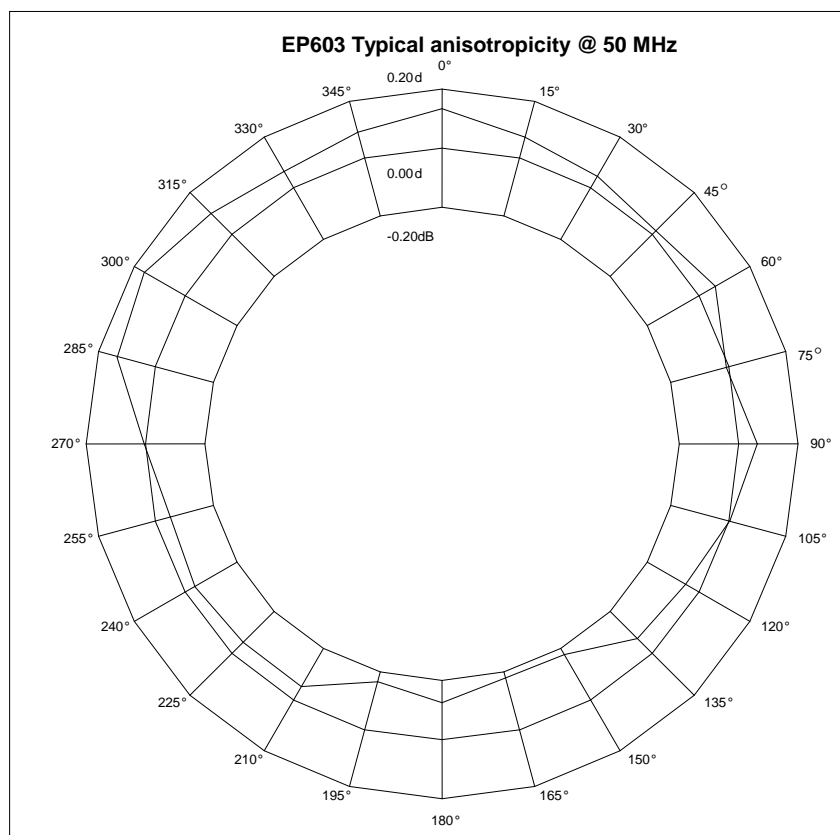
Frequency range	300 kHz – 18 GHz
Level range	0.17 – 170 V/m
Overload	> 350 V/m
Dynamic range	60 dB
Linearity	0.4 dB @ 50 MHz/0.3 – 170 V/m
Resolution	0.01 V/m
Sensitivity	0.17 V/m
Flatness	3 – 8200 MHz 1.4dB 1 – 12000 MHz 2.4 dB 0.6 – 18000 MHz 3.8 dB (With frequency correction OFF)  0.3 – 18000 MHz 0.4 dB (Typical with frequency correction ON)
Isotropy	0.4 dB (0.2 dB typical @ 50 MHz)
Sensors	Six monopoles
X/Y/Z reading	Simultaneous sampling of the components
Battery reading	10 mV res.
Temperature reading	0.1 °C res.
Internal data memory	Serial number Date calibration Calibration Factor SW release.
Battery	Panasonic ML621S 3V 5mA/h rechargeable Li-Mn
Operation time	80 h @ 0.4 S/sec 28 Hz filter 60 h @ 5 S/sec 28 Hz filter
Recharge time	48h for maximum autonomy
Dimensions	17 mm sphere 17 mm sensor 53 mm overall
Weight	23g including FO weight (1m)
Operating temperature	-10° - +50°
Software for PC	YES
Optical fiber connector	HFBR-0500
Tripod adapter	¼ - 20 UNC female

### 1.11 Typical frequency response with correction OFF EP603



**Fig. 1-5** EP603 typical frequency response with correction OFF

### 1.12 Typical anisotropy @ 50 MHz EP603



**Fig. 1-6** EP603 Typical anisotropy @ 50 MHz

### 1.13 Battery management EP600/EP601/EP602/ EP603

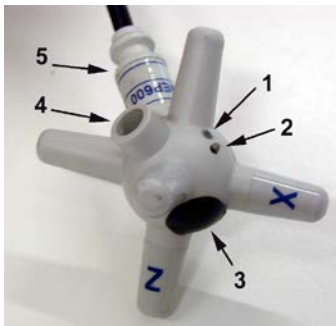
PMM EP600/EP601/EP602/EP603 has an internal Li-Mn rechargeable battery. To charge it use the provided EP600 CHARGER (see chapter 4). The EP600 CHARGER manages the battery charging taking it to full charge automatically.

Nevertheless this type of battery allows partial charge without damages expect for the ageing due to the number of cycles.

The table below shows the typical discharge values of a new battery according to the charge time.

TABLE 1-4 Battery management PMM EP600/EP601/EP602/EP603		
	Filter 28Hz Rate 0.2 sec [ 5 Sample/sec ]	Filter 28 Hz Rate 2.5 sec [ 0.4 Sample/sec ]
Charge time [h]	Discharge time [h]	Discharge time [h]
1	3	5
2	4	8
4	8	12
8	13	21
12	18	31
24	32	56
36	45	70
48	60	80

## 1.14 Housing and connectors



**Fig. 1-7** Plastic housing

1. ON-OFF Led
2. ON-OFF pushbutton
3. Battery compartment and closure
4. Charger connector receptacle
5. Fiber optic holder and ID label



**Fig. 1-8** Optical connectors

BLUE = Transmitter

GREY = Receiver

## 1.15 Standard accessories

Accessories and documents supplied with PMM

EP600/EP601/EP602/EP603:

- Battery charger EP-600 CHARGER
- AC adapter EP-600 CHARGER
- International plugs (UK, USA)
- Italian plug;
- Fiber optic adapter, Blue
- Fiber optic adapter, Grey
- Fiber optic cable FO-EP600/10 (length: 10m)
- Optical-RS232 converter 8053-OC
- USB-RS232 converter
- Tripod mounting adapter
- Mini tripod
- Nylon adapter ¼" Withworth
- Carrying case
- Software CD-ROM
- Operating Manual
- Calibration Certificate
- Service form

## 1.16 Options

Options to order separately:

- PMM 8053B Hand-held metering unit
- PMM SB-10 Switching Control Box
- Fiber optic cable FO-EP600/10 (length: 10m)
- Fiber optic cable FO-EP600/20 (length: 20m)
- Fiber optic cable FO-EP600/40 (length: 40m)
- Optical-RS232 converter 8053-OC
- 8053-OC-PS Power Supply
- TR-02A tripod
- TT-01 Telescopic extension

## 2 - Operation

### 2.1 Foreword

None

### 2.2 Inspection

Once received the instrument, check:

- packing integrity
- instrument and accessories integrity
- contents, according to the check list attached to this manual



### WARNING

**If anything is found damaged or missed, immediately contact your Dealer.**

### 2.3 Ambient

Store instrument and accessories in clean, dry environment free of dust and acid vapours.

Follow requirements for temperature and humidity:

Operation:

- Temperature -10° to +40° C
- Humidity < 90% RH

Storage:

- Temperature -20° to + 70° C
- Humidity < 95% RH

### 2.4 Return for service

Every part of the instrument, included the battery, can only be replaced by NARDA, when the instrument needs repair or is malfunctioning, please contact the NARDA Support center.

When the instrument needs to be sent to NARDA for repairs please complete the questionnaire enclosed with this Operating Manual making sure you fill in all the details relative to the service requested.

In order to minimize repair time, please describe the nature of the failure. If the failure occurs only under certain conditions, please provide details on how we may recreate the same condition in order to identify the fault.

If possible, please reuse the original packaging, making sure the instrument is wrapped in heavy paper or plastic.

Alternatively, use a strong box filled with shockproof material, place enough material all around the equipment so that the unit is stable and firmly blocked inside the box.

Whilst packing, pay special care in protecting the unit's front panel.

Seal the box firmly before shipment.

Mark the box: FRAGILE HANDLE WITH CARE.

### 2.5 Cleaning

To clean the equipment use only dust-free, non-abrasive dry cloths.



### WARNING

**To avoid damage never use any kind of solvent, acid, or similar to clean the instrument.**

- 2.6 Probe support** The conical holder and the extension fiber optic FO-EP600/10 are essential for proper operation. The optional tripod PMM TR-02 is highly recommended for positioning the EP600/EP601/EP602/EP603 at the required height and distance.
- 2.7 Coupling between probe and conductive surfaces** Close proximity of the probe to conductive surfaces can cause direct coupling (capacitive or inductive) with the field sensing dipoles. Additional measurement uncertainty due to coupling can be limited to 1dB by respecting these minimum distances between the probe and any conductive surface:
- 250 mm, for frequencies 100 kHz - 3 MHz
  - 150 mm, for frequencies 3 MHz - 10 MHz
  - 100 mm, for frequencies > 10 MHz
- 2.8 Coupling between probe and operator's body** Accuracy characteristics are referred to non-perturbed electric fields. Always use a fiber optic extension of proper length to keep the probe far away from operator's body.
- 2.9 Multiple sources** Measuring complex electromagnetic fields as produced by multiple RF sources of different frequencies does require isotropic and broadband field probes, as well as fiber optic connections to eliminate errors due to scattering and pick-up effects. PMM EP600/EP601/EP602/EP603 perfectly meets these requirements.

## 2.10 Connecting EP600/ EP601/EP602/EP603

### 2.10.1 RS232 Connection

Requirements to connect the probe PMM EP600/EP601/EP602/EP603 to PC RS232 port:

#### NOTE

Some PC models may not provide enough power through the DB9 connector to supply the optical/RS232 adapter 8053-OC. In such cases install the separate power adapter model 8053-OC-PS between the optical/RS232 adapter 8053-OC and the PC (see chapter “Accessories”).

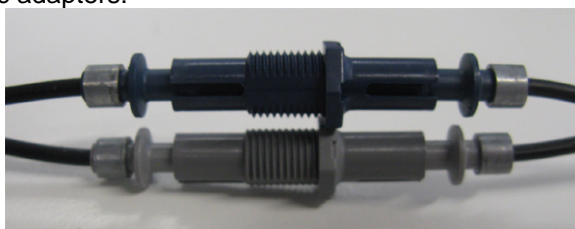
- Connect the 8053-OC to the first available PC RS232 port, directly or with the supplied serial extension cable



- match the colors of the EP600/EP601/EP602/EP603 fiber optic connectors with the colors of the fiber optic adapters:



- match the colors of the FO-EP600/10 extension connectors with colors of the fiber optic adapters:



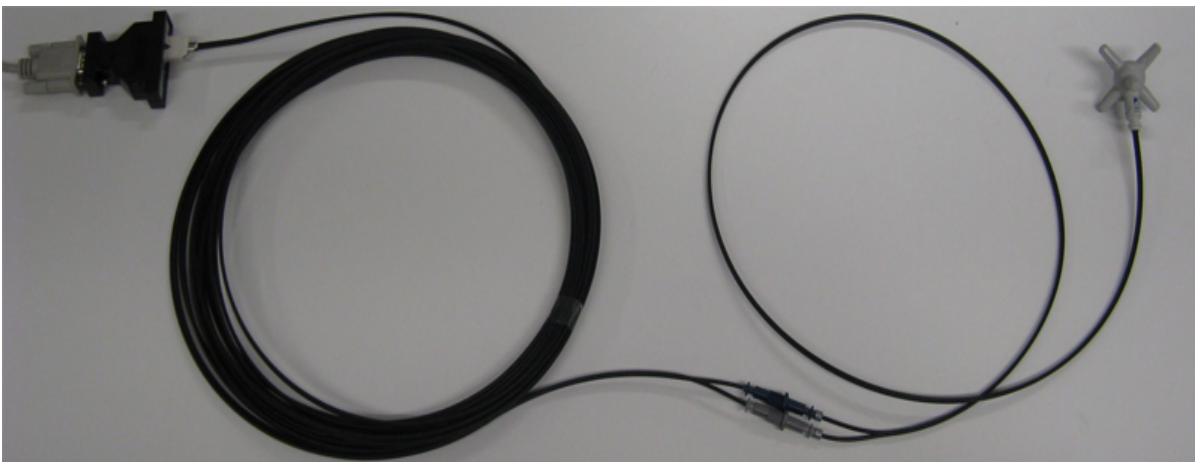
- at one extremity the extension optic cable FO-EP600/10 is terminated with a shaped connector. Respect the connection sense when connecting the same into the shaped receptacle OPTIC LINK of the 8053-OC adapter.



## WARNING

Do not connect/disconnect the optic fibre by applying force to the fiber optic cable directly: this may damage the optical connection. Always hold the connectors with your fingers firmly to connect/disconnect the optic fibre.

Presence of dust, dirt or particles of any nature on the optical connecting surfaces must be carefully prevented.



**Fig. 2-1** RS232 connection of EP600/EP601/EP602/EP603 with FO-EP600/10 extension

## 2.10.2 USB Connection

### NOTE

### WARNING



Requirements to connect the probe PMM EP600/EP601/EP602/EP603 to PC USB:

In some cases the 8053-OC connected with an USB HUB or USB extension might not work properly. Connect the 8053-OC to an USB port of PC directly.

Install the supplied driver software before connecting the USB-RS232 adapter; the driver can also be downloaded directly from the following Web site <http://www.manhattan-products.com/en-US/support/downloads/product/708-usb-to-serial-converter>

- Connect the USB-RS232 adapter to the first available PC USB port
- Connect the 8053-OC to the USB-RS232 converter



- match the colors of the EP600/EP601/EP602/EP603 fiber optic connectors with the colors of the fiber optic adapters:



- match the colors of the FO-EP600/10 extension connectors with colors of the fiber optic adapters:



- at one extremity the extension optic cable FO-EP600/10 is terminated with a shaped connector. Respect the connection sense when connecting the same into the shaped receptacle OPTIC LINK of the 8053-OC adapter.



## WARNING

Do not connect/disconnect the optic fibre by applying force to the fiber optic cable directly: this may damage the optical connection. Always hold the connectors with your fingers firmly to connect/disconnect the optic fibre.

Presence of dust, dirt or particles of any nature on the optical connecting surfaces must be carefully prevented.



**Fig. 2-2** USB connection of EP600/EP601/EP602/EP603 with FO-EP600/10 extension

### 2.10.3 Connection of fiber optic extension FO-EP600/10

The 10 m extension FO-EP600/10 is supplied with the PMM EP600/EP601/EP602/EP603 as standard accessory, together with the two fiber optic adapters – grey and blue (see picture below).



#### NOTE

Some PC models may not provide enough power through the DB9 connector to supply the optical/RS232 adapter 8053-OC. In such cases install the separate power adapter model 8053-OC-PS between the optical/RS232 adapter 8053-OC and the PC (see chapter “Accessories”).

#### WARNING

Do not connect/disconnect the optic fibre by applying force to the fiber optic cable directly: this may damage the optical connection. Always hold the connectors with your fingers firmly to connect/disconnect the optic fibre. Presence of dust, dirt or particles of any nature on the optical connecting surfaces must be carefully prevented.

## 2.11 EP600/EP601/EP602/EP603 installation

Unexpected variations of the probe position may vary the field measurements. Make sure the probe is steadily installed by using the recommended standard or optional accessories.

### 2.11.1 EP600/EP601/EP602/EP603 installation on the conical holder

Using the conical holder supplied with the PMM EP600/EP601/EP602/EP603 as support for the same is essential for correct measurements.

An inadequate support might significantly influence the measurements results; hence it is highly recommended to make use of the supplied conical holder as support for the probe.

To mount the PMM EP600/EP601/EP602/EP603 on the conical holder:

- place the conical holder vertical on a stable surface



- Apply the probe to the conical holder as shown in the picture, having the fiber optic passing through the slot of the conical holder. The picture below shows how to hold the probe between your fingers.



- Rotate the probe 45° counterclockwise:



- Pull the probe gently downwards until the probe plug is locked in the conical holder top.



- The installation is now completed.



**Fig. 2-3** EP600/EP601/EP602/EP603 mounted on conical holder

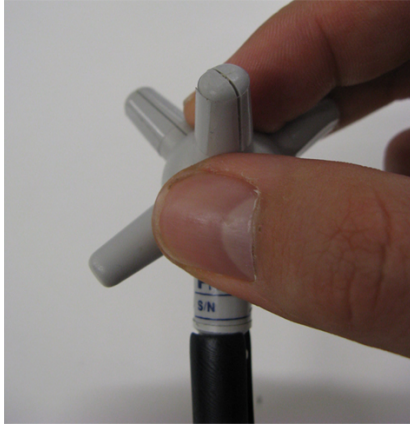
 **NOTE**

As a general rule, when measuring the field from a transmitting antenna it is advisable to position the probe supporting devices perpendicular to the antenna polarization, particularly for frequencies in the range of megahertz.

**2.11.1.1 EP600/EP601/  
EP602/EP603  
removal  
from the conical  
holder**

To remove the PMM EP600/EP601/EP602/EP603 correctly from the conical holder:

- Hold the probe and conical holder in vertical position
- Hold the probe as shown in the picture. Handle the probe with care.



- With the conical holder in vertical position, gently rotate the probe of 45° clockwise. The probe will be automatically released from the conical holder.



- The EP600/EP601/EP602/EP603 removal from conical holder is completed.



**2.11.2 EP600/EP601/  
EP602/EP603  
installation  
on tripod  
PMM TR-02**

It is recommended to make use of the optional tripod PMM TR-02 to position the PMM EP600/EP601/EP602/EP603 as required by the reference standards. Maintaining the same hardware configuration contributes to improve the measurement repeatability (see chapter "Accessories").

Fix the EP600/EP601/EP602/EP603 conical holder to the tripod TR-02A by means of the screw at the top or by means of the swivel PMM 8053-SN.



**Fig. 2-4** EP600/EP601/EP602/EP603 on TR-02A



**Fig. 2-5** EP600/EP601/EP602/EP603 on TR-02A with PMM 8053-SN

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## 3 – Measurements

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### 3.1 Foreword

The following procedures and measurement methods apply to electromagnetic field sources present in industrial, medical, research, residential and telecommunication applications..

### 3.2 Preliminary

Before starting measuring electromagnetic fields (EMF) potentially dangerous, it's advisable to determine the known characteristics of the sources and their possible propagation characteristics. This will allow for a better evaluation of the field distribution and for selecting the correct measuring equipments and procedures.

The source characteristics may include:

- type of generator and radiated power
- carrier frequency or frequencies (i)
- modulation
- polarization of transmitting antenna
- duty cycle, width and repetition frequency for pulsed modulations
- type of antenna and characteristics (gain, size, radiation diagram etc.)
- the number of sources, including those out of the probe bandwidth

To know for propagation evaluation:

- distance between source and point of measurement
- presence of RF absorbing or reflecting structures that may influence the field intensity.

#### 3.2.1 Spurious signals

The operation with diode-based field sensors does require considering possible effects due to spurious signals, like:

- **Multiple sources.** Diodes feature RMS response only for low level signals. In presence of two or more strong signals the probe readings are higher than the real RMS value of the field in the corresponding bandwidth.
- **Pulse modulation.** At high levels the diode response is linear. Consequently, in presence of pulsed signals of low duty cycle the probe tends to read values higher than the real average value. This must be particularly considered for radar signals.
- **Sensitivity to light.** The Schottky diodes employed in some field probes are sensitive to light, including infrared. In such cases it's advisable to avoid direct exposition to the light sources.
- **Perturbing structures** . Metallic and in general conductive surfaces and structures can influence the field probe readings. Field probes must be operated at a proper distance from such structures.

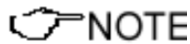
- 3.3 General requirements** The basic components of a field measuring equipment are:
- field probe (field sensor and transducer)
  - connecting cables
  - metering and data processing equipment
- 3.3.1 Probes** As a general rule the field probes must respect the following conditions:
- High rejection to spurious signals
  - No perturbation of the field surrounding the sensors
  - Such connecting cables e.g. fiber optics that do not perturb the field to measure
  - Known response to the operating ambient
- 3.3.2 Connections** The connection between field probe and metering equipment transfer the data relevant to the measurements and the probe/converter settings without influencing the measure.  
Also, unwanted couplings and noise pick-up must be avoided.  
Fiber optic connections do perfectly meet the requirements.
- 3.3.3 Metering equipment** The metering/data processing equipment is designed so that the probe signals or data are properly read, displayed and stored.
- 3.4 Basic functional checks** Some basic functional checks are:
- check of the proper probe operation
  - check for the readings not varying significantly when rotating the probe along one of its axis
- 3.5 Measurement procedures** The measurement procedures must minimize:
- Risks of exposure of personnel to hazardous electromagnetic fields
  - Measurement errors
  - Interferences
  - Damages to the equipment

### 3.6 Preventing measurement errors

To prevent influencing the field measurements the operator, vehicles etc. should stay away of 5 meters from the field sensor; the same should not be located near metallic or conductive surfaces and objects.

**From the definition of difference of potential between two points:**

$$V_{21} = - \int_{r_1}^{r_2} \vec{E} dr$$



We obtain that, with constant difference of potential, when the distance between the two given points diminishes, the field strength increases.

Example: the field strength present between the two plates of a condenser at a distance of 0,1 m and with 100 V applied is of:

$$E = \frac{100V}{0,1m} = 1KV/m$$

To remark that a voltage of 100 V applied in these conditions produces a field strength of 1000 V/m, i.e. much higher than the applied voltage.

3.7

Void

3.8

Void

### 3.9 PMM EP600/EP601/EP602/EP603 operation



The EP600/EP601/EP602/EP603 field probe is allocated in a spherical plastic housing with 6 orthogonal monopoles that allow for immediate identification of the electric field vectors (axis).

The PMM EP600/EP601/EP602/EP603 is supplied from an internal battery that can be recharged by the charge EP600 CHARGER supplied with.

#### NOTE

**One full charge cycle before operation is recommended to obtain the maximum autonomy.**

The PMM EP600/EP601/EP602/EP603 can be switched ON by shortly pressing the pushbutton, after that the LED is sequentially turned on with **green, red and blue indications** as a test for the same; then the LED will blink **red**, this meaning the EP600/EP601/EP602/EP603 is ready for the operation.

#### NOTE

**The PMM EP600/EP601/EP602/EP603 cannot be switched OFF by the pushbutton.**

The PMM EP600/EP601/EP602/EP603 automatically turns OFF when:

- after 180 sec. the fiber optic has been disconnected or the communication with PC is not established; use the operative command **#00e n\*** (see chapter 6) to set the time before the EP600/EP601/EP602/EP603 auto-switches off.

#### WARNING

**The command #00e n\* is available with Firmware release 1.12 or higher**

- when the battery voltage is below 2.05V (the battery voltage is displayed by the software WinEP600).

- when the Software WinEP600 is closed

#### WARNING

**Do not expose the probe to a field higher than the max. allowed. Field strengths exceeding the allowed may cause severe probe damage whether it is connected or not, either turner ON or OFF.**

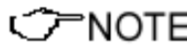
#### WARNING

**The fiber optic must be connected or disconnected by holding it by the connectors only. Pulling the fiber optic cable may cause severe damages to the PMM EP600/EP601/EP602/EP603 and to the fiber optic cable itself.**

**Dust and dirt must be prevented to be in between the optical connections.**



The EP600/EP601/EP602/EP603 can be connected to the PC via fiber optic either when ON or OFF.



When making measurements with PMM EP600/EP601/EP602/EP603 the power supply must be ALWAYS removed.



The min. battery voltage allowed for proper operation is of 2,05 V; it is displayed by the PC software WinEP600. Lower values do require recharging the battery.



The max. battery autonomy is of approx. 80 hours (with Filter 28 Hz and Rate 2.5 sec), according to the filter setting.



The internal battery can be replaced at factory only; in case of damage or incorrect operation contact your Dealer.



It is recommended to fully recharge the battery before long-term storage of the probe; a full recharge shall be performed every 4 months since then.

### 3.10 Applications

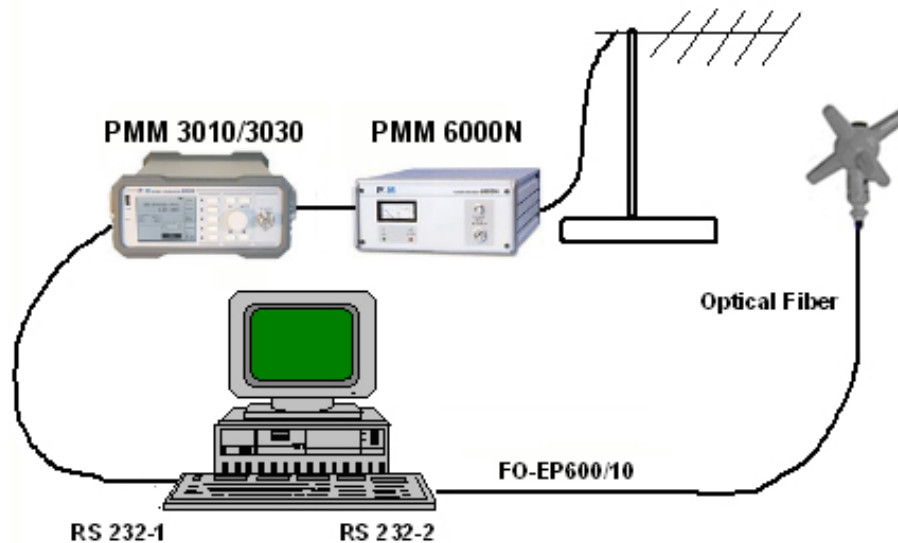
The PMM EP600/EP601/EP602/EP603 field probe is connected to the user's PC via fiber optic and the optic to serial converter (see chapter Operation).

#### 3.10.1 EMC

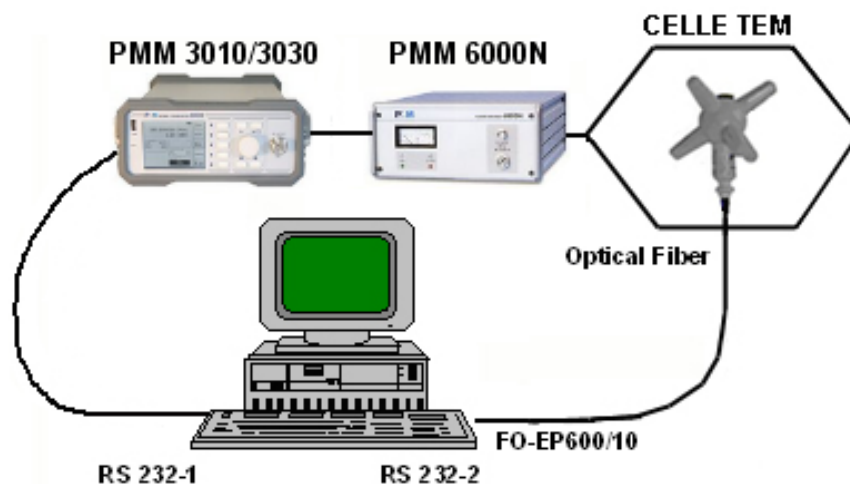
The wide frequency range and small size allow for using the PMM EP600/EP601/EP602/EP603 in EMC applications for monitoring the field strength during radiated immunity tests in open site, TEM/GTEM and anechoic chamber.

The optional accessory PMM SB10 allows for controlling up to 10 field probes at the same time. Up to five PMM SB10 can be connected together to control up to 50 field probes.

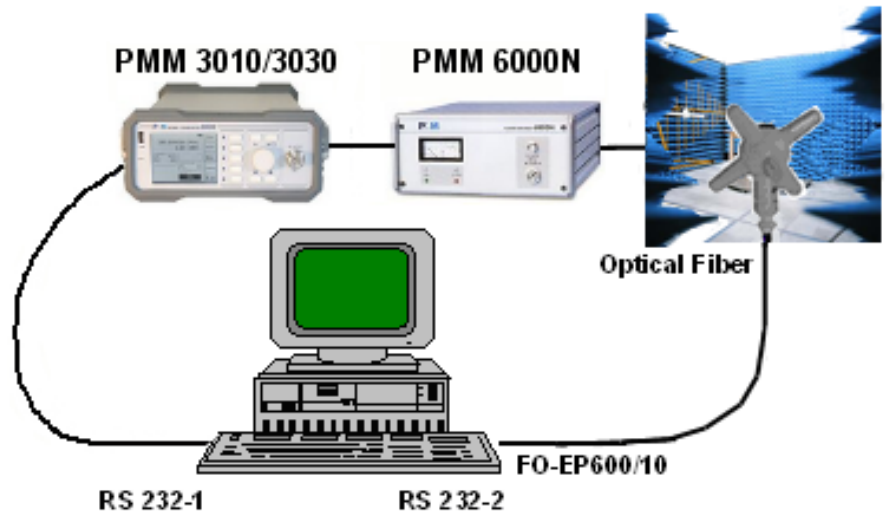
Examples of measuring configurations:



**Fig. 3-1** PMM EP600/EP601/EP602/EP603 in open site



**Fig. 3-2** PMM EP600/EP601/EP602/EP603 in TEM cell



**Fig. 3-3** PMM EP600/EP601/EP602/EP603 in Anechoic Chamber

3.10.2

Void

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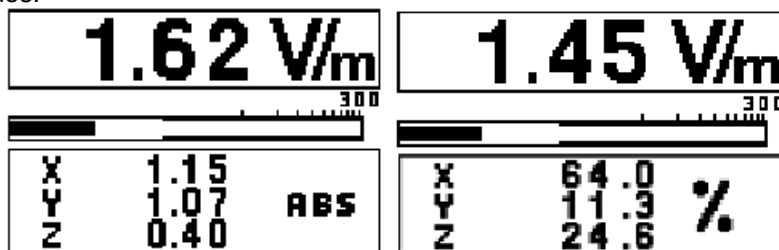
### 3.11 Operating PMM EP600/EP601/ EP602/EP603 with 8053B (Option)

The EP600/EP601/EP602/EP603 can be connected and operated by the meter PMM 8053B.

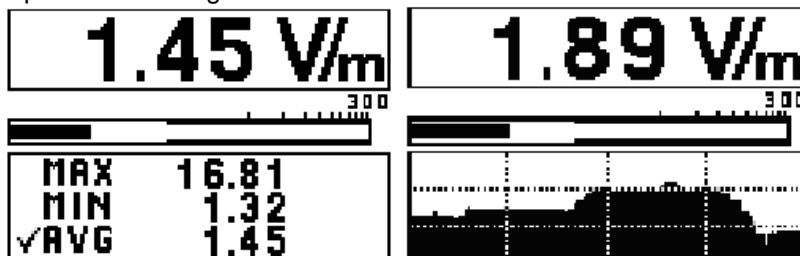


Fig. 3-4 EP600/EP601/EP602/EP603 with 8053B

- Display of field strength in **ABS/%**, **MIN-MAX/AVG**, **MIN-MAX/RMS** modes.



- Graph of field strength in **PLOT** mode.



- Field strength data recording in **Data Logger** mode.

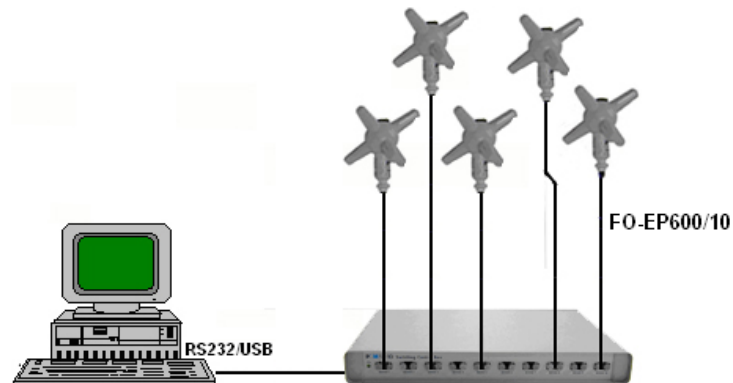


**NOTE**

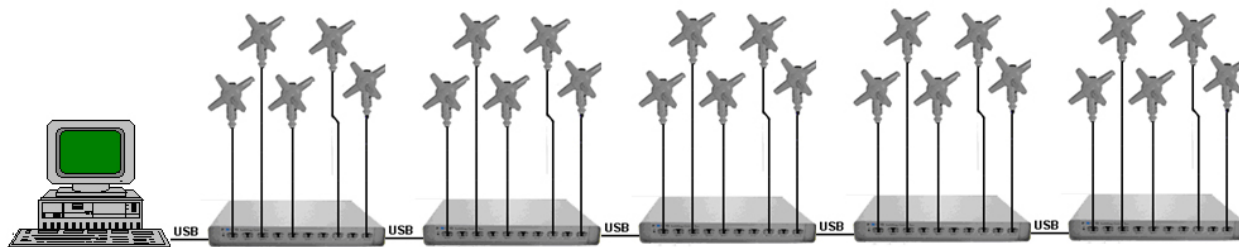
For further information on configuration and operation with PMM 8053B, please refer to the operation manual supplied with it.

### 3.12 Operating EP600/ EP601/EP602/ EP603 with PMM SB10 (Option)

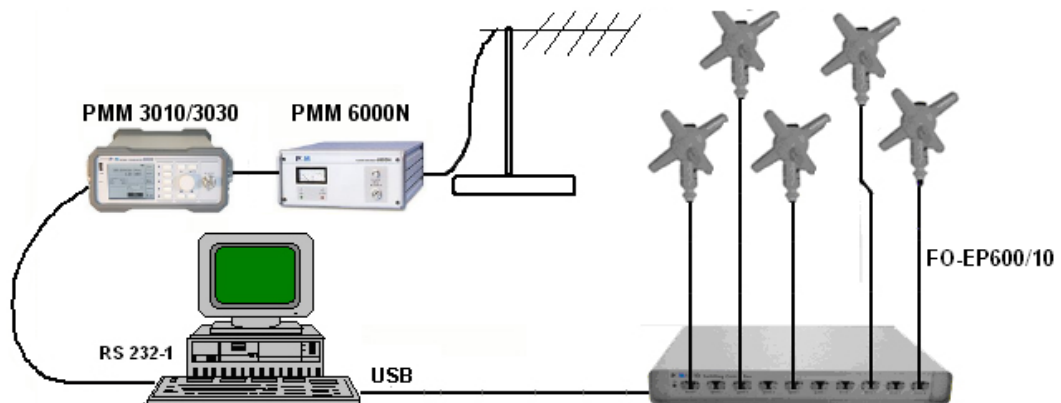
The optional accessory PMM SB10 allows for controlling up to 10 field probes at the same time. Up to five PMM SB10 can be connected together to control up to 50 field probes.



**Fig. 3-5** PMM EP600/EP601/EP602/EP603 with one SB-10

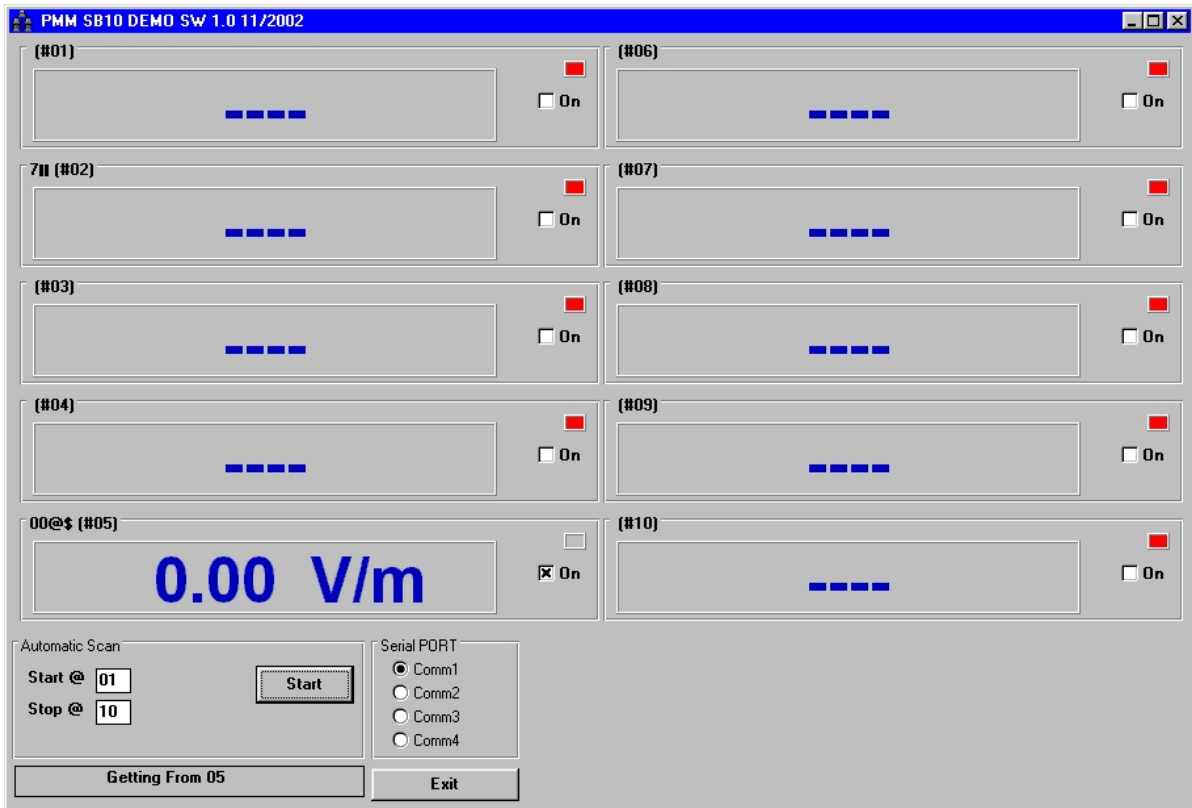


**Fig. 3-6** PMM EP600/EP601/EP602/EP603 with five SB-10



**Fig. 3-7** PMM EP600/EP601/EP602/EP603 with SB-10 in open site

The PC software supplied with the PMM SB10 allows for simultaneous displaying of the field strength measured by each single field probe.



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## 4 – Battery charger EP600 CHARGER

### 4.1 Foreword

The probe EP600/EP601/EP602/EP603 internal circuitry is supplied by a rechargeable Li-Mn internal battery to recharge by means of the battery charger EP600 CHARGER connected to the mains by means of the supplied adapter.

The EP600 CHARGER is intended for this application only; any other use or application is strictly forbidden.

EP600 CHARGER is intended for operation on desk; its special design allows for keeping the probe under charging in correct and safe position. Inside the EP600 CHARGER a microprocessor controls and checks the recharging operation.

The LED shows the charging status.

The adapter supplied with the EP600 CHARGER works with mains voltages from 100 to 240 VAC, 50/60 Hz. Different socket adapters are supplied with.



**Fig. 4-1** AC adapter



**Fig. 4-2** EP600 CHARGER

### 4.2 AC adapter

Always connect the AC adapter to the PMM EP600 CHARGER prior to connect to the mains.



**Output: DC, 10 - 15 V, ~ 500 mA**

**Connector polarity:**



#### 4.2.1 AC mains plug

If required to replace the AC mains plug, remove the installed and install the proper one.

### 4.3 EP600 CHARGER

The following conditions apply to all specifications:

- Operating temperature: -10° to +50 °C.

#### 4.3.1 Specifications

**TABLE 4-1 Characteristics and specifications of the battery charger EP600 CHARGER**

##### Characteristics

Charging is stopped when removing the probe

Microprocessor control with autostart

Charging status Led

Self-test

Safety timer

AC adapter supplied

##### Specifications

Supply voltage	3.8V 5mA (Max)
Supported battery type	Panasonic ML621S 3V 5mA/h Li-Mn
Max. recharging time for max. autonomy	48h
Operating temperature	-10° ÷ +50°
Dimensions (LxDxH)	60x60x75mm
Weight	130 g

#### 4.3.2 EP600 CHARGER components

##### Description:

- 1 – Knob and Spring
- 2 – Charging connector
- 3A – Charging status Led
- 3B – DC Supply connector



Fig. 4-3 EP600 CHARGER components

NOTE

Attempting to charging batteries of different types or dry cells may cause explosion of the same and is strictly forbidden.

NOTE

The internal battery of EP600/EP601/EP602/EP603 can be replaced by the Factory only. In case of failure or incorrect operation please contact the Dealer.

NOTE

The minimum voltage level for proper operation is of 2,05V; lower voltages do require recharging the battery.

NOTE

It is recommended to fully recharge the battery before long-term storage of the probe; a full recharge shall be performed every 4 months since then.

NOTE

The max. battery autonomy is of approx. 80 hours (with Filter 28 Hz and Rate 2.5 sec), according to the filter setting.

NOTE

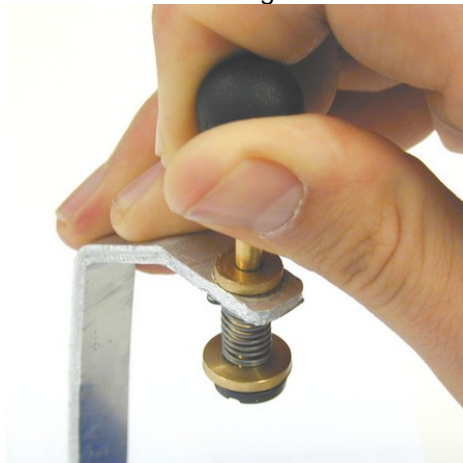
When making measurements with PMM EP600/EP601/EP602/EP603 the power supply must be ALWAYS removed.

#### 4.4 Installing EP600/ EP601/EP602/ EP603 on EP600 CHARGER

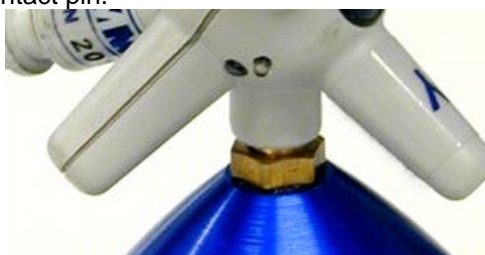
A first complete charging cycle is recommended to achieve the max autonomy.

To install the probe EP600/EP601/EP602/EP603 on the battery charger EP600 CHARGER:

- place the EP600 CHARGER on a flat, stable surface
- hold and lift up the knob as shown in figure



- Insert the EP600/EP601/EP602/EP603 on the EP600 CHARGER in correspondence of the threaded contact pin. Do not spin the probe to avoid damaging the contact pin.



#### NOTE

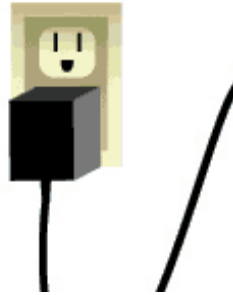
- Release progressively the knob until rubber tip holds the EP600/EP601/EP602/EP603 housing downwards.



- Connect the AC adapter to the EP600 CHARGER first, then to the mains.



- Plug the AC adapter to the mains



- Check the Led status as per the table below:



**Fig. 4-4** EP600/EP601/EP602/EP603 on EP600 CHARGER

**Table 4-2 EP600 CHARGER Led status - Start up phase**

Fix	Green	The EP600 CHARGER is supplied but without load (battery not present or disconnected).
Fix	Red	The charging circuit is overloaded (the output is OFF for 30 seconds before attempting a new charging cycle).

**Table 4-3 EP600 CHARGER Led status - Charger phase**

Blinking	Green	The battery is under charge
Fast Blinking	Red	Charge ended for maximum time limit reached [ 60 hours ]
Slow Blinking	Orange	Charge ended for maximum time limit reached without 12 hours of stabilisation.
Fast Blinking	Orange	Charge ended for maximum time limit reached with 12 hours of stabilisation.



**The complete charging cycle is of 48 hours; the charge is completed when the Led of EP600 CHARGER blinks orange.**

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## 5 – WinEP600 and SetAddEP600

### Operating instructions

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#### 5.1 Foreword

This chapter is the installation and operation guide of the PC Softwares WinEP600 and SetAddEP600 Utility supplied with the PMM EP600/EP601/EP602/EP603 field probe.

The SetAddEP600 is a utility that integrates the PMM SB10 Switching Control Box and the PMM EP600/EP601/EP602/EP603.

When several PMM EP600/EP601/EP602/EP603 are connected to the PMM SB-10 each of them need to be set with a different address.

With the SetAddEP600 Utility you can associate an address at each PMM EP600/EP601/EP602/EP603 connected to the PMM SB-10.

#### 5.2 PC minimum requirements

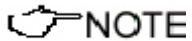
- Processor: Pentium
- 16 Mb RAM
- 10 Mb free space on hard disk;
- Operating system Windows<sup>™</sup>, XP/Vista/Win7.



**Software and Utility updates can be downloaded from the web page [www.narda-sts.it](http://www.narda-sts.it).**

### 5.3 Installation

To install the WinEP600 and the SetAddEP600 on PC from the supplied CD-ROM proceed as follows:

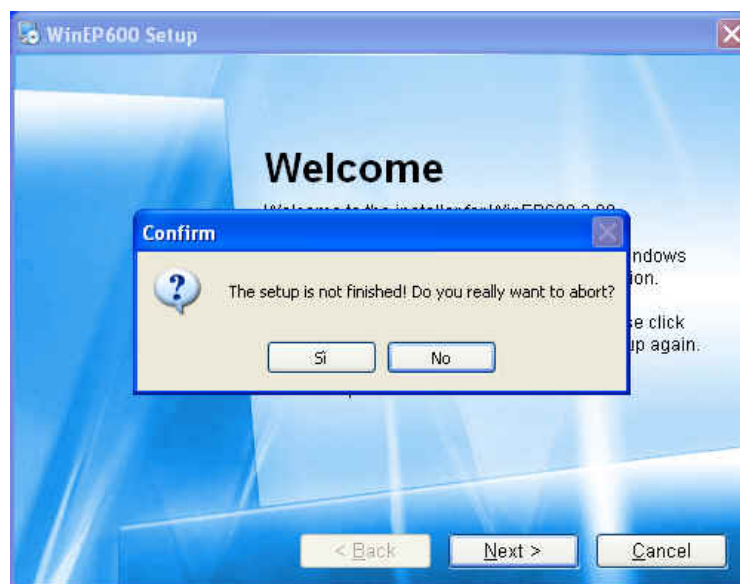


**Do not connect the PMM EP600/EP601/EP602/EP603 to the PC until the installation is completed.**

Insert the WinEP600 CD into the PC CD-ROM driver.  
In Computer Resources double click on the corresponding CD-ROM driver.  
To start the installation double click on the **WinEP600** icon.

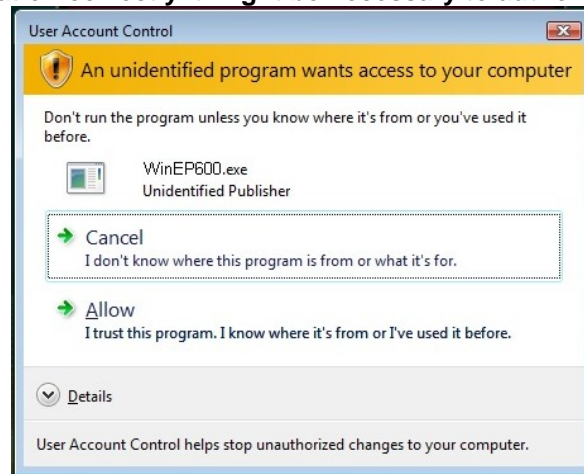


The installation can be aborted by clicking on **Cancel**:

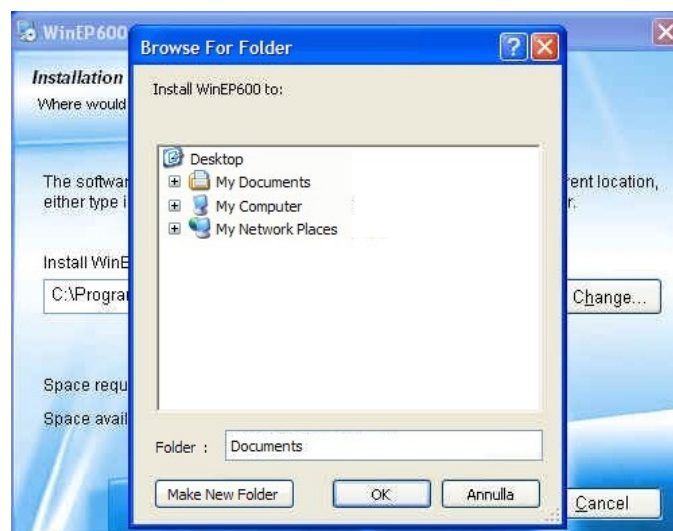
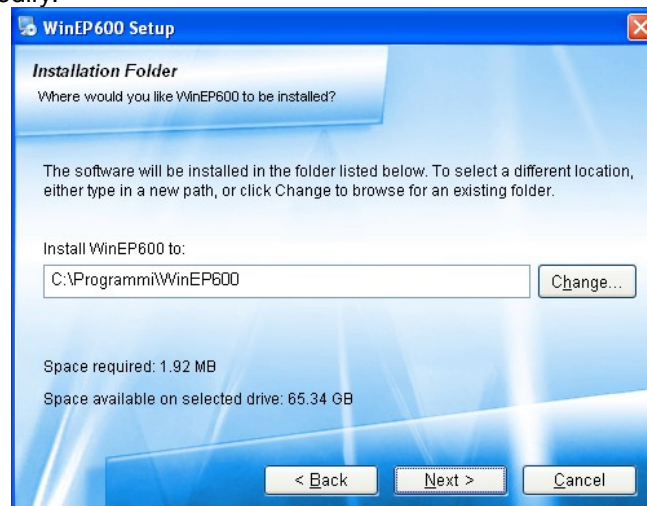


**NOTE**

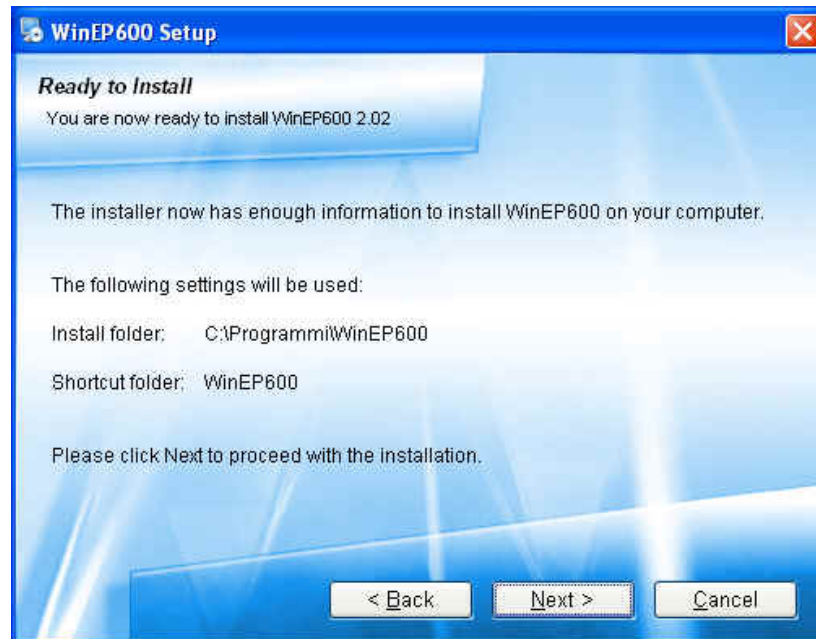
In Windows Vista most programs are blocked for computer protection. To start the installation correctly it might be necessary to authorize the operation.



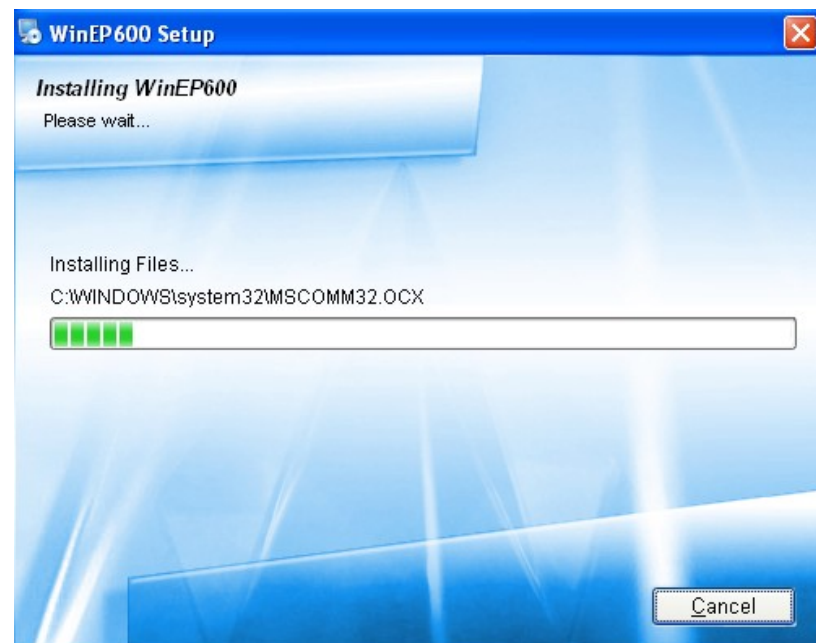
The installation folder must be specified. Click **Next** to confirm the default folder or **Change** to modify.



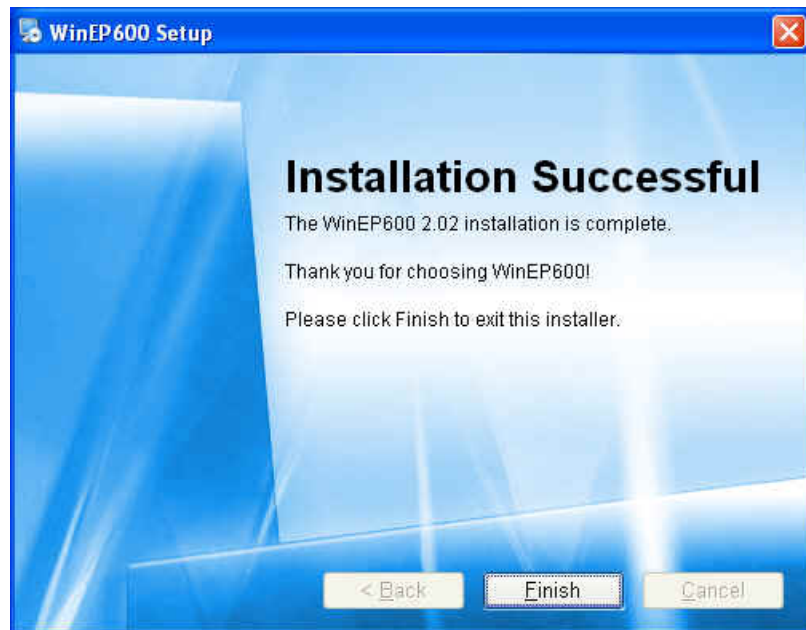
Click **Next** to proceed installing.



The installing status is displayed then:



Click **Finish** to complete and exit the installer.  
The folder **WinEP600** and **SetAddEP600** are created under **Programs** with the icon **WinEP600** on desktop.



Create the **SetAddEP600** shortcut on your desktop.



#### 5.4 COM port settings with 8053-OC

Connect the 8053-OC to the PC first serial port available (for more details see chapter "Installation").

#### NOTE

In some PC models the power delivered through the DB9 connector may be not enough to supply the optical/serial converter 8053-OC. In such cases, the external power supply adapter mod. 8053-OC-PS must be connected between the PC and the optical/serial converter 8053-OC.

#### NOTE

With the 8053-OC optical/serial converter the software search for the probe PMM EP600/EP601/EP602/EP603 on the first available serial port.

To set a specific serial port:

##### 5.4.1 WinEP600 COM port settings

- Select the icon WinEP600 with the right mouse button;
- Select Properties;
- Add the command COMM=N preceded by a space (in capital letters) at the end of the Destination field where N indicates the serial port to be used; for example, if the EP600 is connected to port 2, add the command COMM=2.

#### NOTE

The assigned COM port nr. must be between 1 and 9.



#### NOTE

- In some operating system the Destination field is enclosed in double quotation marks (""); in this case, the command COMM=N, preceded by a space must be outside as in the example below;



- then confirm by selecting Apply

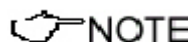
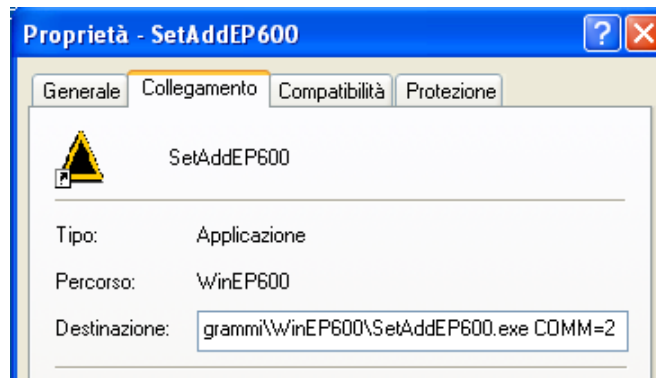
#### 5.4.2 SetAddEP600 COM port settings

- Select the icon SetAddEP600 with the right mouse button;
- Select Properties;
- Add the command COMM=N preceded by a space (in capital letters) at the end of the Destination field where N indicates the serial port to be used; for example, if the EP600 is connected to port 2, add the command COMM=2.



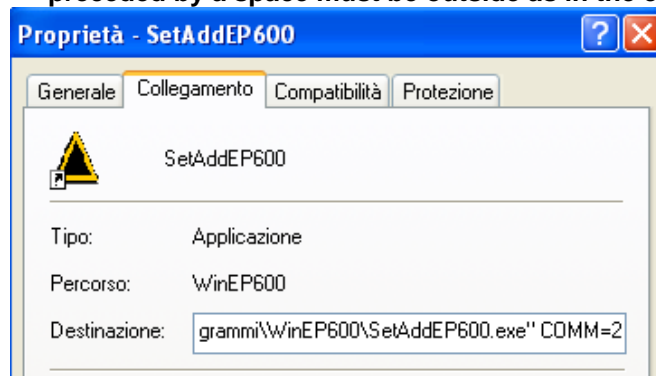
**NOTE**

**The assigned COM port nr. must be between 1 and 9.**



**NOTE**

- In some operating system the Destination field is enclosed in double quotation marks (""); in this case, the command COMM=N, preceded by a space must be outside as in the example below;



- then confirm by selecting Apply

## 5.5 COM port setting with adapter USB-RS232

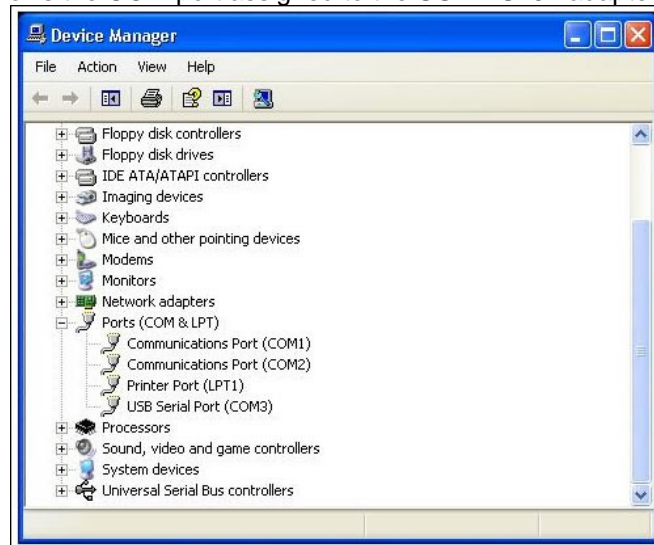
Connect the USB-RS232 adapter to the PC USB port and wait for the “**new hardware installation**” procedure. Drivers supplied with the adapter can be used as well.

### NOTE

After having installed the USB-RS232 adapter, make sure the assigned COM port nr. is comprised between 1 and 9:

- Enter in **Peripheral management** (Start > Settings> Control Panel > System>Hardware> Device Manager).  
The assigned COM can be found in **Ports (COM & LPT) – USB Serial Port (COMx)**.

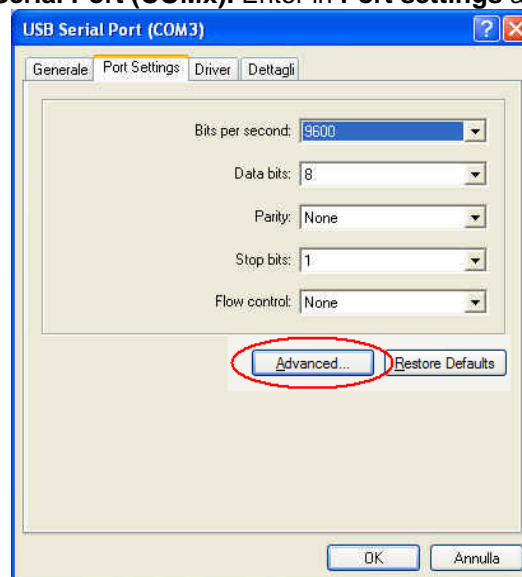
**COMx** shows the COM port assigned to the USB-RS232 adapter.



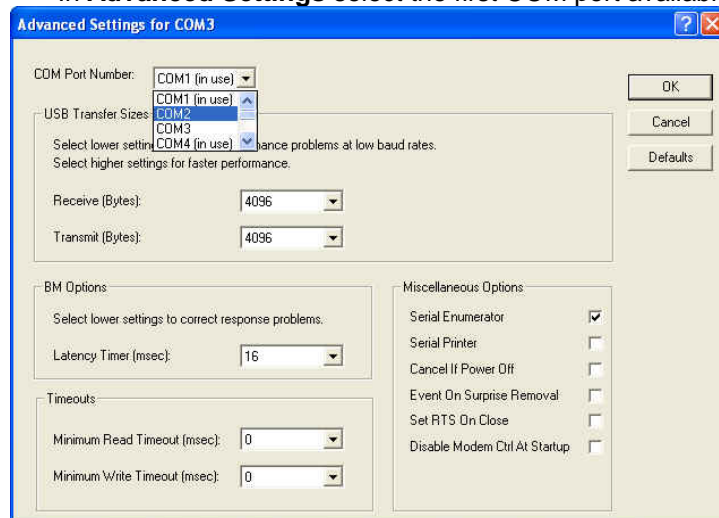
### NOTE

If the adapter is set for a COM port nr. Not comprised between 1 and 9, the settings can be changed as follows:

- To change the **COMx** port, double click the line **Ports (COM & LPT)** and **USB Serial Port (COMx)**. Enter in **Port settings** and **Advanced**.

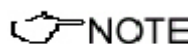


- In **Advanced Settings** select the first COM port available; click **OK**.

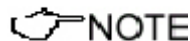


### 5.5.1 WinEP600 COM port settings

- Select the icon WinEP600 with the right mouse button;
- Select Properties;
- Add the command COMM=N preceded by a space (in capital letters) at the end of the Destination field where N indicates the serial port to be used; for example, if the EP600 is connected to port 2, add the command COMM=2.



The assigned COM port nr. must be between 1 and 9.



- In some operating system the Destination field is enclosed in double quotation marks (""); in this case, the command COMM=N, preceded by a space must be outside as in the example below;



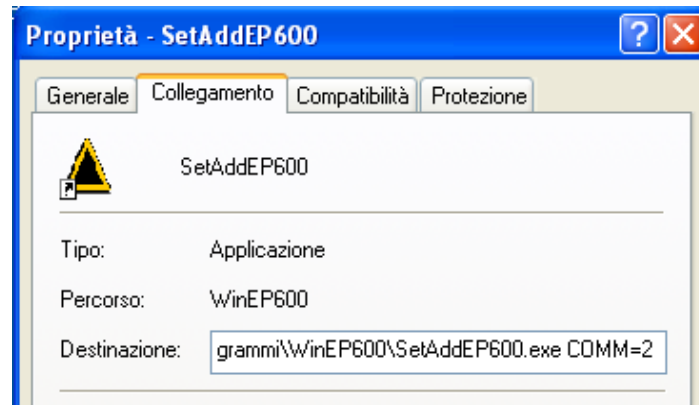
- Then confirm by selecting Apply

### 5.5.2 SetAddEP600 COM port settings

- Select the icon SetAddEP600 with the right mouse button;
- Select Properties;
- Add the command COMM=N preceded by a space (in capital letters) at the end of the Destination field where N indicates the serial port to be used; for example, if the EP600 is connected to port 2, add the command COMM=2.

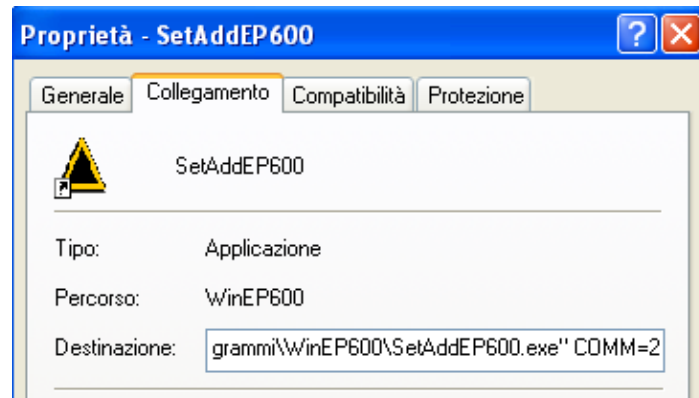
#### NOTE

The assigned COM port nr. must be between 1 and 9.



#### NOTE

- In some operating system the Destination field is enclosed in double quotation marks (""); in this case, the command COMM=N, preceded by a space must be outside as in the example below;



- Then confirm by selecting Apply

## Running WinEP600



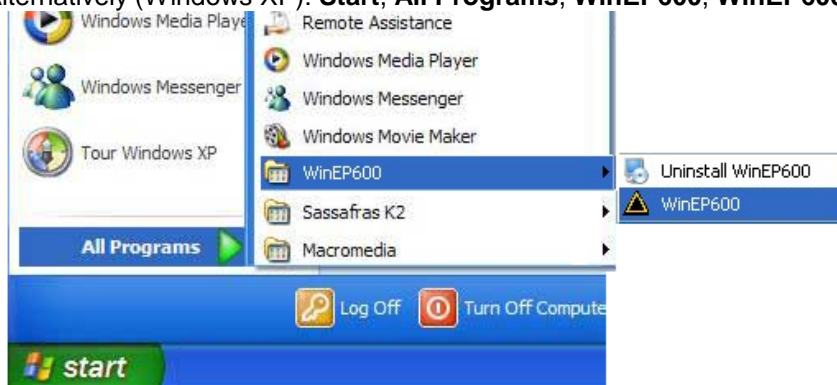
NOTA

Before to start WinEP600, it is recommended to limit the applications running on your computer.

Connect the PMM EP600/EP601/EP602/EP603 to PC and click the icon on desktop.



Alternatively (Windows XP): **Start, All Programs, WinEP600, WinEP600.**

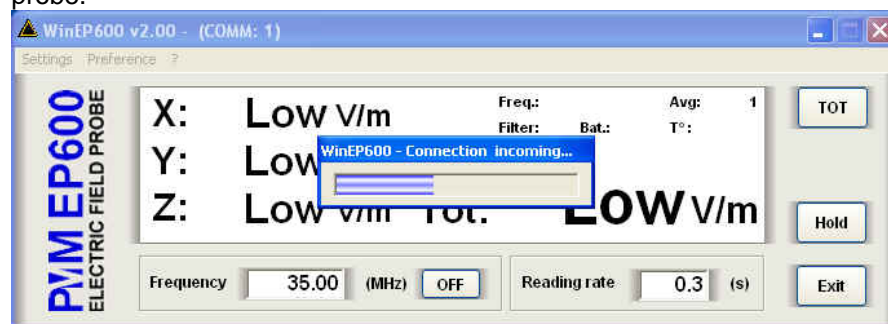


Windows Vista or 7: Click **Windows** (Windows logo), **Programs, WinEP600, WinEP600.**

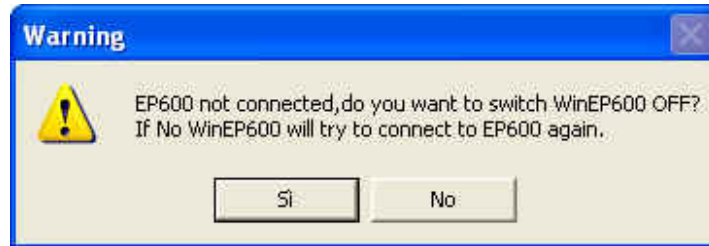
This window is displayed first:



Then, the main window is displayed together with the **WinEP600 - Connection Incoming** indication of the correct communication with the probe.



This message appears when PMM EP600/EP601/EP602/EP603 is not connected or the communication is not established:

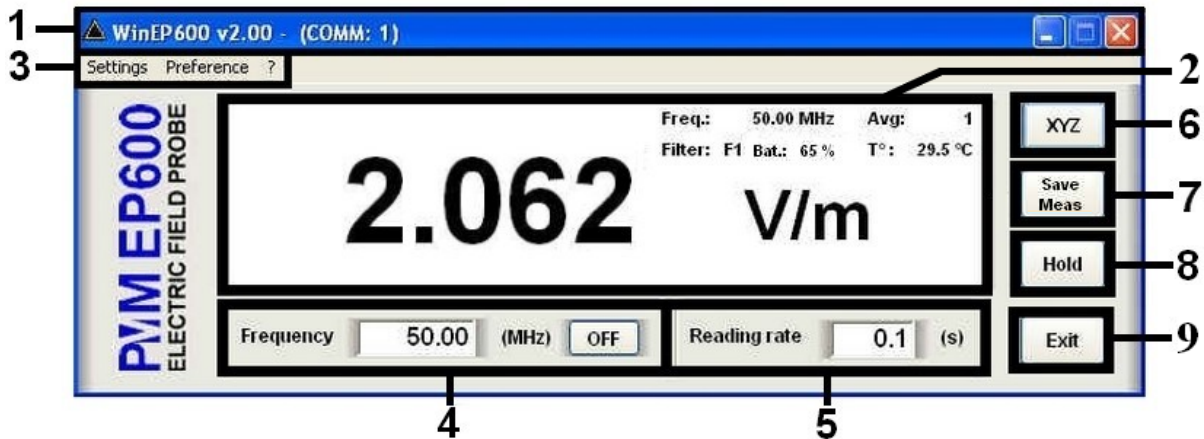


Select **YES** to quit the WinEP600 – the EP600/EP601/EP602/EP603 is switched OFF.

Select **NO** to retry establishing the communication (check the EP600/EP601/EP602/EP603 correct installation before).

### 5.7 Main window contents

Once connected the main window is displayed:

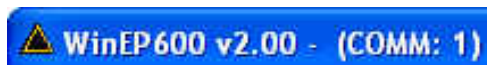


Commands description:

1. Title bar
2. Measurements and settings
3. Settings selection
4. Correction frequency setting in MHz
5. Reading rate in seconds (s)
6. Toggle between total field value or contemporary x - y - z axis readings
7. Button to store the field value (Every time the software starts the button is disabled).
8. Hold/run readings
9. Exit and quit the program

### 5.7.1 Title bar

The software release is shown here, together with the serial port as set in the program properties.



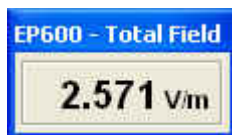
The control buttons allow to minimize to icon, enlarge/restore the main window and exit the program:



When minimizing the main window the information is displayed in the Windows application bar at the bottom of screen.



The field measurement remains displayed on desktop meanwhile.



For more information see par. "Setting/Preference/Minimized UI".

### 5.7.2 Main window displayed measurements

The measurements displayed in the main window are:

- **electric field values** as x - y - z or total (see par. "XYZ / TOT")

*Mode x - y - z*



*Mode Total*



- **Measuring unit** shows the electric field measuring unit; the value is displayed with three decimals. Min. value displayed: 0.010 V/m.

- **Correction frequency** see par. "Frequency setting"

Default: *Freq: 50.00 MHz*

- **Average and Filter** see par. "Settings"


Default: *Avg: 1 Filter: F1*

- **Battery status** displayed in 5% steps. It shows the residual autonomy during measurements and the achieved autonomy during charging.

- **EP600/EP601/EP602/EP603 internal temperature** in °C

### 5.7.3 Frequency correction setting

This setting in MHz recalls the corresponding frequency correction factor stored in the EP600/EP601/EP602/EP603 memory.

 **NOTE**

The graph in chapter 1 shows the correction factor in db as a function of the working frequency.

 **NOTE**

The setting displayed at the first run is the default; the last setting will be displayed then.

The frequency is displayed with two decimals, max. resolution of 0.01 MHz. Press the enter key to enter the set frequency value.




To disable the frequency correction, click OFF; the button toggles to ON for enabling the function when required.



 **NOTE**

When entering the frequency correction value or enabling the function, the "Frequency value" will be updated according to the Reading Time setting.

 **NOTE**

When entering the frequency correction value while in HOLD mode, the new value will be not displayed until the HOLD is released.

 **NOTE**


The following message will appear when entering frequencies out of the PMM EP600/EP601/EP602/EP603 range:




#### 5.7.4 Reading Rate setting

It shows the time interval (in seconds) between subsequent readings.  
Setting resolution of 0.1 s.  
Press the enter key to enter the set frequency value.




 NOTE


The setting displayed at the first run is the default; the last setting will be displayed then.

 NOTE

The minimum time interval between readings is in function of the filter setting. The table Filter (Settings/Filter) show the minimum reading rate allowed.

 NOTE

The max. time interval between readings is of 30 s regardless of the filter setting.

 NOTE

Entering a reading rate not allowed will cause a warning message to appear:



### 5.7.5 XYZ / TOT



Button for selecting the x - y - z or Total mode.  
Max. display resolution: 0.001 V/m.



### NOTE

Click on the button to toggle from XYZ to TOT.



If the field value is outside the nominal level range, the following messages are displayed:

**Ovr** : the field level is higher than 110% of the nominal maximum level (550 V/m for EP601).

**!** : the field level is between 100% and 110% of the nominal maximum level (from 500 to 550 V/m for EP601). The symbol is close to the value.

**\*** : the field level is lower than nominal minimum level. The symbol is close to the value.

- 0.5 V/m per EP601 on the total;
- $0.5 / \sqrt{3}$  per EP601 on the single axis.

**Low** : the field level is lower than 1/15 of the nominal minimum level.

- 0.5 / 15 per EP601 on the single axis;
- $0.5 / (15 \times \sqrt{3})$  per EP601 on the total.

### WARNING

The field value outside the nominal level range could be unreliable.

### 5.7.6 HOLD / RUN



Press HOLD to freeze the readings.  
Click on the button to toggle from HOLD to RUN  
The button XYZ/TOT is active even when in HOLD.

### NOTE

**If the program is exit when in HOLD mode, it will restart in RUN mode.**

### 5.7.7 EXIT



Press **EXIT** to end the program. The current settings are saved and will be recalled at the next start.

Message:



Press **YES** to exit and turn the EP600/EP601/EP602/EP603 off.  
Press **NO** to abort exiting.

## 5.7.8 Settings menu

Settings Preference ?

Commands:

- **Settings:** set Average and Filter
- **Preference:** select program skin and enable the function **Minimized UI**
- **? (Info):** software and product information

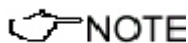
### 5.7.8.1 Settings



**Settings** options:

- **Filter:** the EP600/EP601/EP602/EP603 internal A/D Sigma-Delta converters feature digital filters to improve resolution and sensitivity, as well to reducing interferences. The filters can be selected according to the application requirements: from the faster (F1) to the slower (F8).

To set the required filter click on the corresponding line, which turns blue. The selected filter will be displayed in the main window.



**When selecting a new filter while in HOLD mode, the filter setting indication in the main window will be updated only after toggling to RUN mode.**

Filter					
	Filter(Hz)	Rejection to mains	Settling time(ms)	Max Sample rate(S/s)	Min Reading Rate(s)
F1	28	25dB@60Hz	20	22	0,1
F2	24	25dB@50Hz	23	20	0,1
F3	8	no notch	63	12	0,15
F4	4,7	80dB@60Hz	100	8	0,15
F5	4	65dB@50/60Hz	125	6,6	0,2
F6	4	80dB@50Hz	125	6,6	0,2
F7	3,2	no notch	150	5,9	0,25
F8	2,3	67dB@50/60Hz	200	4,4	0,3

**Filter(Hz):** indication of the filter characteristics

**Rejection to mains:** some filters feature notch filtering at mains frequency to reducing interference

**Settling time (ms):** time required for getting a complete reading

**Max Sample rate (S/s):** A/D conversion speed

**Min Reading Rate (s):** min. time interval between readings of electric field

Normally a fast field measurement is required for faster response and better stability when the field probe controls as feedback for a preset field value the radiated power of a system composed by antenna and RF generator.

However, as faster the measurements as higher the noise is, with consequent reduction of sensitivity.

Slower measurements increase sensitivity but increase the response time and the power consumption.

The PMM EP600/EP601/EP602/EP603 features eight different filters to help finding the most suitable combination of the a.m. parameters for each specific application:

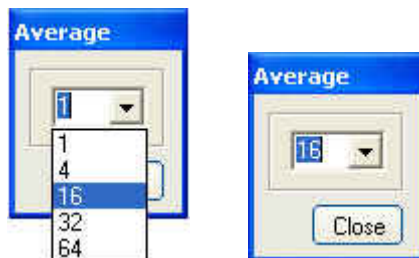
<b>F</b>	<b>Settling time</b>	<b>Power consumption</b>	<b>Sensitivity</b>	<b>Rejection @ 50Hz</b>	<b>Rejection @ 60Hz</b>
<b>1</b>	Very fast	Very low	Low	-----	low
<b>2</b>	Very fast	Very low	Average	Low	-----
<b>3</b>	Fast	Low	Good	-----	-----
<b>4</b>	Average	Average	High	Good	Very high
<b>5</b>	Average	Average	High	High	High
<b>6</b>	Average	Average	High	Very high	Good
<b>7</b>	Slow	High	Very high	good	Good
<b>8</b>	Slow	Very high	Very high	High	High

#### **NOTE**

In normal operation setting the filters F4 - F5 may offer a good compromise in terms of power consumption, sensitivity, settling time and rejection @ 50Hz.



- **Average:** setting of the number (1, 4, 16, 32 or 64) of readings to calculate the arithmetic average (AVG).



## NOTE

When setting **Average = 1**, the readings are not averaged and the current measurements are displayed.

In the example, the average value of the last 16 field readings will be displayed. The “**Avg**” counter shows the progressing of the average calculation, updating according to the “Reading rate” time interval setting.



The message **AVG: OK** will be displayed shortly after completion of the averaging process, then followed by the indication of the preset averaging **Avg: 16**.

Then the process continues in moving Average mode: of the 16 readings block, the older is discarded and the latest is added at the speed of the Reading rate setting.

The process is restarted from the beginning when setting a different Average value.

## NOTE

When toggling from TOT to XYZ mode the Average is reset to re-calculate the field values for each single axis.

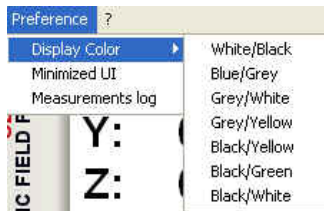


## NOTE

When in HOLD mode, the new Average value is displayed in the main window and is updated only when the HOLD is released.

### 5.7.8.2 Preference

Functions of the **Settings** menu:



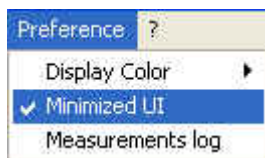
- **Display Color:** selection of different color combinations of the main window among:

#### Background / readings and units

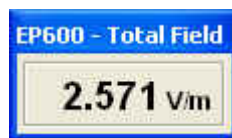
- Blue/Grey
- Grey/White
- Grey/Yellow
- Black/Yellow
- Black/Green
- Black/White



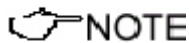
The color of the settings of Freq, Avg, CorFact e Offset will be displayed accordingly.



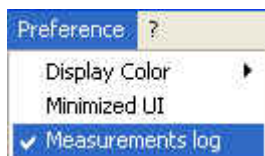
- **Minimized:** enable the function **Minimized UI (Unit Interface)** to keep the field readings displayed on desktop when minimizing the main window on the tray.



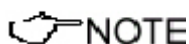
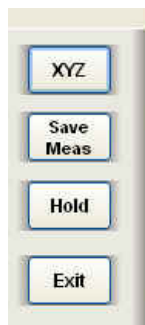
This window can be moved anywhere on the desktop, keeping its final position even at the next minimizing of the main window.



To close this window, restore the main window from the tray and deselect the “Minimized UI” function.

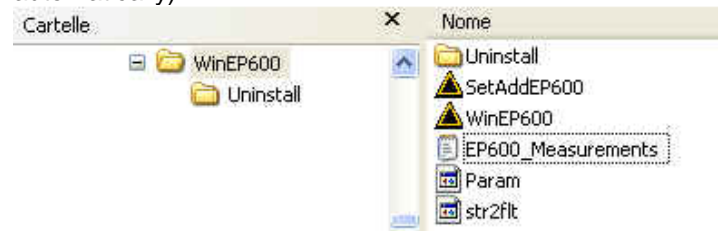


- **Measurements Log:** enable the function **Measurements Log** to display the **Save Meas** button in the main window. The symbol ✓ means that the function is activated.

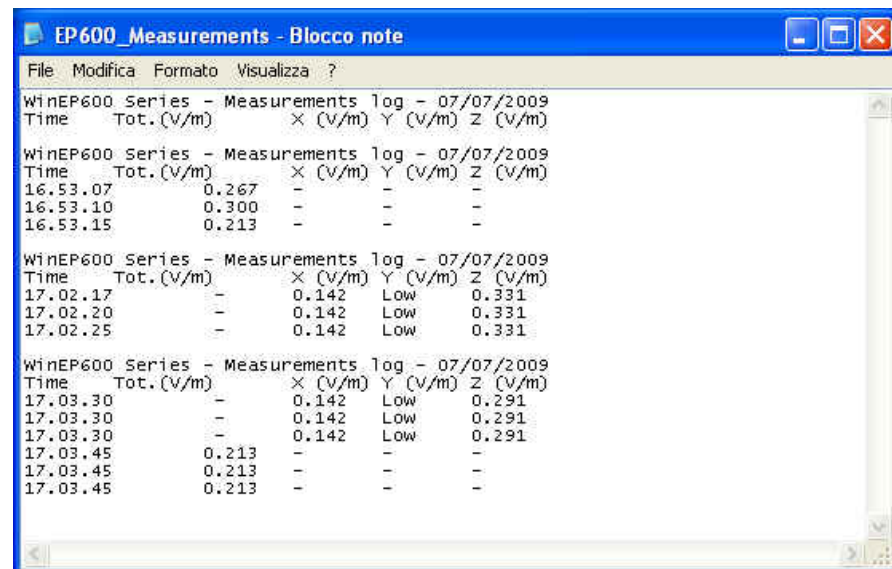


Every time the software starts the function Measurements Log is disabled

Every time the button **Save Meas** is selected, the field value is stored in the file *EP600\_Measurements.txt* (at the first run the file is created automatically).



When the file is saved in TXT format and the table is opened, a huge amount of data are available



For every working session (from starting to closing the software) the following headline will be created in the txt file:

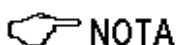
```
WinEP600 Series - Measurements log - dd/mm/yyyy
Time Tot.(V/m) X (V/m) Y (V/m) Z (V/m)
```

**dd/mm/yyyy:** working session date.

**Time:** hour, minute, second of the measurement.

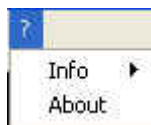
**Tot.(V/m):** Field value in Total mode.

**X(V/m) Y(V/m) Z(V/m):** Field value in x, y and z mode.



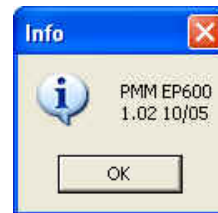
The recorded data can be viewed either as a graph or as a table. By using Word or Excel application, click the Open file command and select "Type of file": "all files"; then find the file to open starting from the directory and follow the necessary path until the file is found.

### 5.7.8.3 ? (Info)

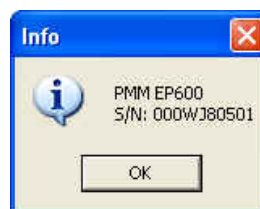


Contents:

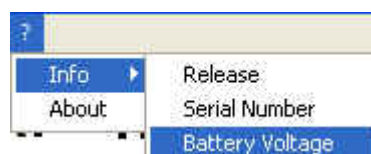
- **Info:** current EP600/EP601/EP602/EP603 firmware version and date, serial number and battery voltage.



Click  to exit.




Click  to exit.



### NOTE

**Battery voltages below 2.11V (5% of charge) are displayed red.**

Click  to exit.

- **About:** Manufacturer information.



## 5.8

### Running SetAddEP600

Connect the PMM EP600/EP601/EP602/EP603 to PC and click the icon on desktop.

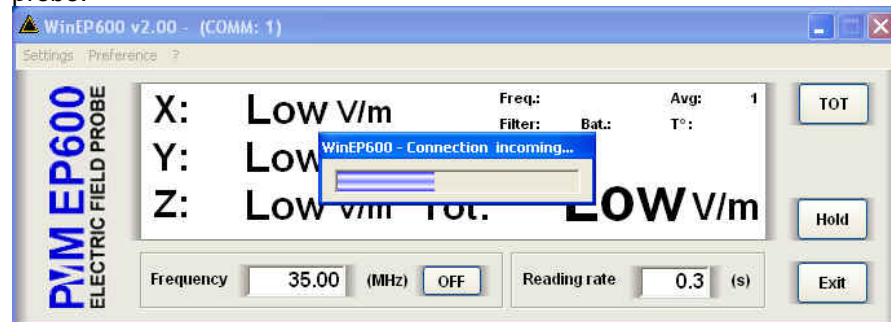


Alternatively (Windows XP): **Start, All Programs, WinEP600, SetAddEP600.**

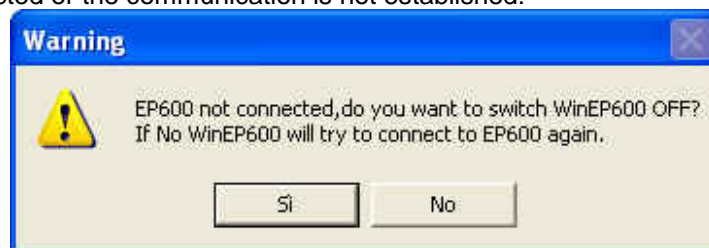


Windows Vista or 7: Click **Windows** (🌐), **Programs, WinEP600, SetAddEP600.**

Then, the main window is displayed together with the **SetAddEP600 - Connection Incoming** indication of the correct communication with the probe.



This message appears when PMM EP600/EP601/EP602/EP603 is not connected or the communication is not established:



Select **YES** to quit the SetAddEP600 – the EP600/EP601/EP602/EP603 is switched OFF.

Select **NO** to retry establishing the communication (check the EP600/EP601/EP602/EP603 correct installation before).

## 5.9 Main window contents

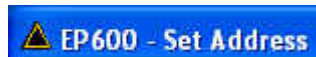
Once connected the main window is displayed:



1. Title bar
2. Probe Data
3. New Address
4. Exit

### 5.9.1 Title bar

The title bar displays the name of the program.



The control buttons allow to minimize to icon and exit the program:

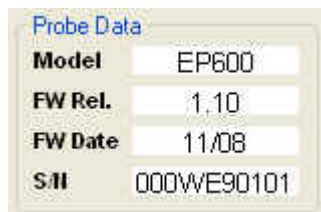


When minimizing the main window the information is displayed in the Windows application bar at the bottom of screen.




### 5.9.2 Probe data

When the communication is established, the probe data displays: probe model, release and data firmware and serial number.



### 5.9.3 New Address

When the communication is established, the window  displays the current probe address.




Enter new address  and press  to store it.

The software will inform that the address program has been successfully stored:



### 5.9.4 Exit


Press  to close the program.

## 5.10

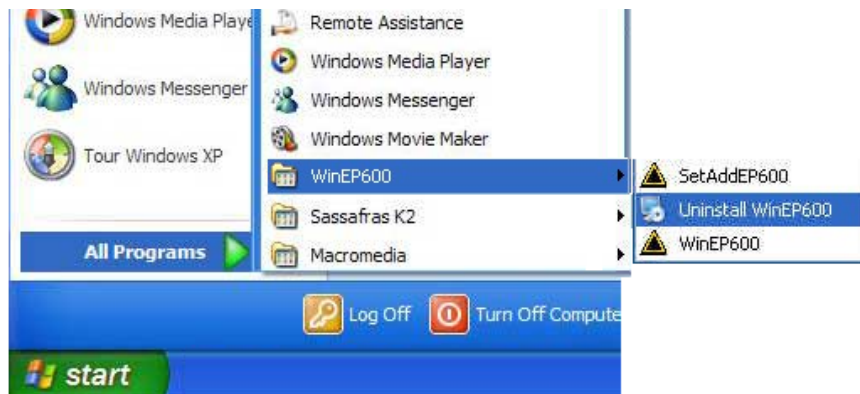
### Uninstalling WinEP600 and SetAddEP600

Disconnect the USB cable (the procedure of “safe disconnection” is unnecessary).

Windows XP: click **Start**

in Windows Vista or 7: click **Windows** 

Then **All Programs, WinEP600, Uninstall WinEP600**.



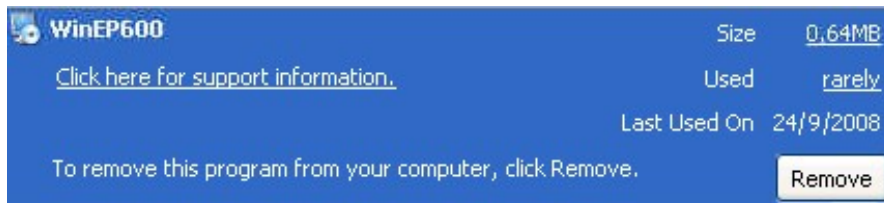
#### NOTE

**If the Uninstaller is not available:**

Disconnect the USB cable (the procedure of “safe disconnection” is unnecessary).

Click **Start, Settings, Control Panel and Add or Remove Programs (Programs and functions for Windows Vista or 7)**.

Find WinEP600 then click **Remove** and follow the instructions.



#### WARNING

**When asked if removing the shared files, answer NO to prevent other programs not to run correctly.**

## Uninstalling the driver of RS232-USB adapter

### NOTE

Apply this method if the driver uninstaller (normally supplied with the hardware) is not available.

Right click **My computer** to access **Properties**



Select **Hardware** and **Device Manager**.

Click **+** to expand **Port (COM and LPT)**.

Right click **USB Serial Port (COM)** then click **Uninstall**



Click **OK** to end.



Once the uninstall is completed the peripheral **USB Serial Port (COM)** will be removed.



## 6 - Communication protocol

### 6.1 Disclaimer

This chapter provides the information required to control the PMM EP600/EP601/EP602/EP603 via the fiber optic connected to a PC and by means of user's own PC software applications. Narda STS S.r.l supports the correctness of the information only, and disclaim for any consequence the use of such information may cause to anybody. The inclusion of Narda's communication protocol into user's or third party software is entirely at the user's risks and responsibility. In no way Narda STS S.r.l shall be liable for damages of any kind consequent to the use of the information provided in this chapter.

### NOTE

**All the following examples are indifferently referred to the PMM EP600, EP601, EP602 and EP603.**

### 6.2 Protocol

The serial communication between PC and PMM EP600/EP601/EP602/EP603 is the RS232 standard or USB (via the USB-RS232 converter). Specifications:

- Rate 9600 Baud
- Start 1 bit
- Stop 1 bit
- No Parity

The commands are composed by an ASCII string delimited by “#” (0x23) and “\*” (0x2A)

Up to FW 1.02 each command must begin with the address which is made of the string “00”.

From FW 1.10 each command starts sending the address which is made of two characters string in the range “00” to “99”.

The address “00” is a special one as it is considered Broadcast while all others must match the address stored in the unit (see command “I”).

In other words the EP600 will always grant all commands starting with “#00” regardless its own address stored.

Broadcast mode is intended when using the EP600 in a NON-BUS way, typically PC directly linked to EP600, or for setting the new address (see command “I”). In this mode the address can be changed even without knowing the current address.

Careful must be taken, however, when the EP600 works on a BUS (for example via SB10) as using the broadcast address all the device sharing the BUS would answer at the same time creating thus a conflict.

Hereafter all example are made using the broadcast address but, of course, they work also using different address. The only restriction is that the address must be made of two characters and the range is “00” to “99”

The answer can be either in ASCII or Binary, according to the command sent. The first character is always like the character sent, and can be used as control marker or synchronization for the answer.

The available commands are of three categories:

- **Query COMMANDs**
- **Setting COMMANDs**
- **Operative COMMANDs**

The commands have this format:

**#00Qcommand(parameters)\*** where:

**#** = command string start

**00** = string always present

**Q** = ? for query commands

**S** for setting commands

**Command** = command string

**(parameters)** = setting parameters value (where present)

**\*** = command string end

#### **NOTE**

At power ON the EP600/EP601/EP602/EP603 is in Master mode, as required by the communication with the hand-held unit 8053B; the EP600/EP601/EP602/EP603 will continue to send the measurement data independent from receiving the commands. For this might be not useful when interfacing to other software, send the command **#00?v\*** to turn the EP600/EP601/EP602/EP603 in Slave mode to answer only when receiving a query.

To save battery the EP600/EP601/EP602/EP603 automatically turns off 180 seconds after receiving a command; use the operative command **#00e n\*** (see table 6-2) to set the time before the EP600 auto-switches off.

**Table 6-1 Query Commands**

Command	Description
<b>?v</b>	<p>This query command <b>#00?v*</b> sends back a string containing information about model, release and date of firmware.</p> <p>Example of reply to the command <b>#00?v*</b>: "<b>vEP600:1.02 10/05;</b>"</p>
<b>?p</b>	<p>This query command <b>#00?p*</b> sends back a string containing information about date of calibration.</p> <p>Example of reply to the command <b>#00?p*</b>: "<b>10/05;</b>"</p>
<b>?b</b> Battery	<p>This query command <b>#00?b*</b> sends back 3 bytes containing information about the voltage of EP600 battery.</p> <p>The array is made of 3 bytes in which the first is the character 'b' followed by 2 bytes expressing a 16bit unsigned integer (<b>nn</b>) in <b>Big</b> Endian notation.</p> <p>To get the battery voltage use the following formula:  <math>V_{battery} = 3 * (nn / 1024 * 1.6)</math></p>
<b>?t</b> Temperature	<p>This query command <b>#00?t*</b> sends back 3 bytes containing information about the temperature of EP600 probe.</p> <p>The array is made of 3 bytes in which the first is the character 't' followed by 2 bytes expressing a 16bit unsigned integer (<b>nn</b>) in <b>Big</b> Endian notation.</p> <p>To get the temperature in degrees Centigrade use the following formula:  <math>T_{ep600} = ((nn / 1024 * 1.6) - 0.986) * 1000 / 3.55</math></p>
<b>?s</b> Serial Number	<p>This query command <b>#00?s*</b> sends back a string containing the serial number of the device</p> <p>Example of reply to the command <b>#00?s*</b>: "<b>s123456789AAAA</b>"</p>
<b>?T</b> Total Field	<p>This query command <b>#00?T*</b> sends back 5 bytes containing information about the <b>total</b> field strength measured by EP600.</p> <p>The array is made of 5 bytes in which the first is the character 'T' followed by 4 bytes expressing a 32bit IEEE floating point number(<b>ff</b>) in <b>Little</b> Endian notation.</p> <p>The figure (<b>ff</b>) represents the square of total field strength (isotropic measure)</p> <p>To get the field strength, the square root must be taken:  <math>V/m = \sqrt{ff}</math></p>
<b>?A</b> All Field Components	<p>This query command <b>#00?A*</b> sends back 13 bytes containing information about field strength measured by EP600 of every <b>single axis</b>.</p> <p>The array is made of 13 bytes in which the first is the character 'A' followed by 12 bytes expressing 3 (X,Y,Z) 32bit IEEE floating point number(<b>ff</b>) in <b>Little</b> Endian notation.</p> <p>The 3 figures (<b>fx,fy,fz</b>) directly represent the field strength of related axis and are expressed in V/m.</p>

**Table 6-2 Setting Commands**

Command	Description
<b>k</b> <sub>fr</sub>	<p>This setting command <b>#00k frq*</b> sets the frequency(<b>frq</b>) to which refer the correction factor.</p> <p>The figure <b>fr</b> is the ASCII string representing the <b>integer</b> frequency multiplied by 100 giving thus the resolution of 10kHz.</p> <p>Once the EP600 has received and granted this command, all measurements will be corrected using the factor stored in factory related to this frequency.</p> <p>Sending a frequency which is out of EP600 range disables frequency correction factor function.</p> <p>The reply is an array made of 5 bytes in which the first is the character 'k' followed by 4 bytes expressing a 32bit IEEE floating point number(<b>ff</b>) in <b>Little</b> Endian notation.</p> <p>The figure (<b>ff</b>) represents the frequency used by the EP600</p> <p>Example of command <b>#00k 10000*</b>: (Set the internal frequency to 100MHz)</p>
<b>f</b> <sub>n</sub>	<p>This setting command <b>#00fn*</b> sets the processing filter (<b>n</b>) used for measurements.</p> <p>The index <b>n</b> must be between 0 and 7.</p> <p>For further information on filters please refer to separated document</p> <p>Example of command <b>#00f2*</b></p>
<b>e</b> <sub>n</sub>	<p>This setting command <b>#00e n*</b> sets the time before the EP600 auto-switches off after receiving a recognized command.</p> <p>Note that this setting is <b>not permanent</b> and it will be kept only while the EP600 is ON. Every time the EP600 is turned off, the default 180 second is taken.</p> <p>The argument <b>n</b> is expressed in second e should be lower than 10800 (3 hours).</p> <p>The replay to this command is 'e' if it has been granted and 'x' if the argument is out of range (in which case the default 180 is taken).</p> <p>Example of command <b>#00e 600*</b> : (sets the switch off time to 10 minutes)</p>

Table 6-3 Operative Commands	
Command	Description
<b>@c</b>	<p>This setting command <b>#00@c*</b> temporarily puts the EP600 in “Storing Mode” allowing thus storing a new address.          As this permission lasts only for 1 second, the command “I” should be issued closely.          This command has not a reply.</p> <p>Example of command <b>#00@c*</b></p>
<b>@I<sub>addr</sub></b>	<p>This setting command <b>#00@I<sub>addr</sub>*</b> sets the address used for communication protocol.          It is made of a 2 character string int range “00” to “99”.          Neither spaces nor punctuation are allowed between “#@00” and addr .</p> <p>This setting command is executed only if sent within 1 second since the command “c”          The reply is the address itself if it has been granted otherwise “ERR” if the EP600 was not in Storing Mode          Example of command <b>#00@0I53*</b> which sets the address to “53”. Therefore, all following commands starting with <b>#53.....*</b>, in addition to <b>#00....*</b>, will be granted.</p>

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## 7 – DLL Function reference guide

### NOTE

All the following examples are indifferently referred to the PMM EP600, EP601, EP602 and EP603.

### NOTE

The DLL library manages only the broadcast address (“00”).

#### 7.1 C language

##### 7.1.1 PMM\_CreateProbe()

```
int PMM_CreateProbe( const char *name, HANDLE *probeHandle, const char *commPort);
```

##### **Purpose:**

Establishes communications with a specified probe.

##### **Return Value:**

Returns an integer status code. The numeric value of 0 indicates no error occurred. See Status Code chapter for an error code description.

##### **Input Parameters:**

const char \*name: PMM EP60X model name Ex.: EP601

const char \*commPort: Serial communication port name Ex.: COM1, COM3...COM99

##### **Output Parameters:**

HANDLE \* Handle

### NOTE

Use `#include<windows.h>` for the HANDLE type data.

Special value that is used to refer to this probe for subsequent function calls after it is created.

##### 7.1.2 PMM\_RemoveProbe()

```
int PMM_RemoveProbe(const HANDLE probeHandle);
```

##### **Purpose:**

Closes the communications port and releases memory back to the system.

##### **Return Value:**

Returns an integer status code. The numeric value of 0 indicates no error occurred. See Status Code chapter for an error code description.

##### **Input Parameters:**

HANDLE probeHandle; as returned from the *CreateProbe* function

##### **Output Parameters:**

None

##### 7.1.3 PMM\_Firmware()

```
int PMM_Firmware(const HANDLE probeHandle, char *firmware, int *arraySize);
```

##### **Purpose:**

Gets the probe's firmware version.

##### **Return Value:**

Returns an integer status code. The numeric value of 0 indicates no error occurred. See Status Code chapter for an error code description.

##### **Input Parameters:**

HANDLE probeHandle; as returned from the *CreateProbe* function

##### **Output Parameters:**

Pass-by-reference character string: Specifying the length of string

#### 7.1.4 PMM\_ProbeName()

```
int PMM_ProbeName(const HANDLE probeHandle, char *name, int *arraySize);
```

**Purpose:**

Return the probe name identification information.

**Return Value:**

Returns an integer status code. The numeric value of 0 indicates no error occurred. See Status Code chapter for an error code description.

**Input Parameters:**

HANDLE probeHandle; as returned from the *CreateProbe* function

**Output Parameters:**

The name is placed in the user allocated string buffer.

#### 7.1.5 PMM\_Model()

```
int PMM_Model(const HANDLE probeHandle, char *model, int *arraySize);
```

**Purpose:**

Return the probe model identification information.

**Return Value:**

Returns an integer status code. The numeric value of 0 indicates no error occurred. See Status Code chapter for an error code description.

**Input Parameters:**

HANDLE probeHandle; as returned from the *CreateProbe* function

**Output Parameters:**

The model is placed in the user allocated string buffer.

#### 7.1.6 PMM\_CalibrationDate()

```
int PMM_CalibrationDate(const HANDLE probeHandle, char *calibrationDate, int *arraySize);
```

**Purpose:**

Returns the probe's the last calibration date. Not available on older probes.

**Return Value:**

Returns an integer status code. The numeric value of 0 indicates no error occurred. See Status Code chapter for an error code description.

**Input Parameters:**

HANDLE probeHandle; as returned from the *CreateProbe* function

**Output Parameters:**

Pass-by-reference character string: calibrationDate: probe's calibration date.

arraySize: the length of the string.

#### 7.1.7 PMM\_ReadBattery()

```
int PMM_ReadBattery(HANDLE probeHandle, float *battery);
```

**Purpose:**

This function reads the probe's battery status.

**Return Value:**

Returns an integer status code. The numeric value of 0 indicates no error occurred. See Status Code chapter for an error code description.

**Input Parameters:**

HANDLE probeHandle

**Output Parameters:**

Pass-by-reference float battery: Is the battery's status in Volt.

#### 7.1.8 PMM\_ReadTemperature()

```
int PMM_ReadTemperature(HANDLE probeHandle, float *temperature);
```

**Purpose:**

This function reads the probe's internal temperature.

**Return Value:**

Returns an integer status code. The numeric value of 0 indicates no error occurred. See Status Code chapter for an error code description.

**Input Parameters:**

HANDLE probeHandle

**Output Parameters:**

Pass-by-reference float temperature. The numeric value of the probe internal temperature in degrees Celsius.

#### 7.1.9 PMM\_SerialNumber()

```
int PMM_SerialNumber(const HANDLE probeHandle, char *serialNumber, int *arraySize);
```

**Purpose:**

Returns the probes serial number.

**Return Value:**

Returns an integer status code. The numeric value of 0 indicates no error occurred. See Status Code chapter for an error code description.

**Input Parameters:**

HANDLE probeHandle

**Output Parameters:**

Pass-by-reference character string serialNumber: probe's serial number.  
arraySize: the length of the string.

#### 7.1.10 PMM\_SetFrequency()

```
int PMM_SetFrequency(const HANDLE probeHandle, int Frequency);
```

**Purpose:**

Sets the frequency to which refer the correction factor. Once the EP600 has received and granted this command, all measurements will be corrected using the factor stored in factory related to this frequency.

**Return Value:**

Returns an integer status code. The numeric value of 0 indicates no error occurred. See Status Code chapter for an error code description.

**Input Parameters:**

HANDLE probeHandle, int Frequency multiplied by 100 giving thus the resolution of 10kHz.

Sending a frequency which is out of EP600 range disables frequency correction factor function.

**Output Parameters:**

None

#### 7.1.11 PMM\_SetFilter()

```
int PMM_SetFilter(const HANDLE probeHandle, int FILTER);
```

**Purpose:**

Sets the processing filter (n) used for measurements.

**Return Value:**

Returns an integer status code. The numeric value of 0 indicates no error occurred. See Status Code chapter for an error code description.

**Input Parameters:**

HANDLE probeHandle, int range Accepts values 0 – 7

**Output Parameters:**

None

#### 7.1.12 PMM\_SetTimeout()

```
int PMM_SetTimeout(int tout);
```

**Purpose:**

Sets the communication timeout with PMM EP600 series.

**Return Value:**

Returns an integer status code. The numeric value of 0 indicates no error occurred. See Status Code chapter for an error code description.

**Input Parameters:**

int tout in milliseconds. Default value is 500 ms.

**Output Parameters:**

None

#### 7.1.13 PMM\_SetAutoOffTime()

```
int PMM_SetAutoOffTime(const HANDLE probeHandle, int Time);
```

**Purpose:**

Sets the time before the EP600 auto-switches off after having received a recognized command.

**Return Value:**

Returns an integer status code. The numeric value of 0 indicates no error occurred. See Status Code chapter for an error code description.

**Input Parameters:**

HANDLE probeHandle, int time in seconds. Accepts values 180(3 minuts) – 10800(3 hours)

**Output Parameters:**

None

#### 7.1.14 PMM\_ReadTotalField()

```
int PMM_ReadTotalField (const HANDLE probeHandle, float &XYZField);
```

**Purpose:**

Returns the total combined field of the X, Y and Z Axis.

**Return Value:**

Returns an integer status code. The numeric value of 0 indicates no error occurred. See Status Code chapter for an error code description.

**Input Parameters:**

HANDLE probeHandle; as returned from the *CreateProbe* function

**Output Parameters:**

Pass-by-reference float. The combined fields of X, Y and Z axis.

#### 7.1.15 PMM\_ReadAxisField

```
PMM_ReadAxisField (const HANDLE probeHandle, float *xField, float *yField, float *zField);
```

**Purpose:**

To read the field values from the X-axis, Y-axis and Z.

**Return Value:**

Returns an integer status code. The numeric value of 0 indicates no error occurred. See Status Code chapter for an error code description.

**Input Parameters:**

HANDLE probeHandle

**Output Parameters:**

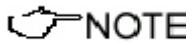
Pass-by-reference float. Returns the X, Y and Z fields.

## 7.2 Visual Basic

From the Project menu, select References to call up the References dialog box, and then click Browse to find your new type library (PMM\_EP60X.tlb). Once you have located it, press OK. Visual Basic will automatically register the library for you the first time you reference it. Make sure that your library ("PMM\_EP60X") has been checked in the references List, and then close the dialog box.

## 7.3 Status Code

TABLE 7-1 Status Code	
0	OK
1	Bad Handle
2	Unable to open port
3	Not connected
4	Wrong response
5	No response
6	Invalid parameter
7	Commport busy
8	Timeout
9	Commport error
10	Problem writing comport
11	Read comport error
12	Bad connection string
13	Value cannot be set
14	Probe not supported
15	Probe over range
16	Probe under range
17	Error closing commport
18	Error purging commport



The file **PMM\_EP60X.DLL** and **PMM\_EP60X.TLB** are installed automatically by the **WinEP600 Setup.exe** in the system folder **C:\Windows\System32\**.

## 8 - Accessories

### 8.1 Foreword

This chapter explains how to use the accessories of PMM EP600/EP601/EP602/EP603.

The following general indications apply to all accessories.

### 8.2 Inspection

Check the packing integrity.



**If anything is found damaged or missed, immediately contact your Dealer.**

**Check the accessories with reference to the packing list included in the package.**

### 8.3 Ambient

Store the accessories in clean, dry environment free of dust and acid vapours.

Follow requirements for temperature and humidity:

Operation:

- Temperature -10° to +40° C
- Humidity < 90% RH

Storage:

- Temperature -20° to + 70° C
- Humidity < 95% RH

### 8.4 Return for service

Every part of the accessories, included batteries, can only be replaced by NARDA, when the instrument needs repair or is malfunctioning, please contact the NARDA Support center.

When an accessory needs to be sent to NARDA for repairs please complete the questionnaire enclosed with this Operating Manual making sure you fill in all the details relative to the service requested.

In order to minimize repair time, please describe the nature of the failure. If the failure occurs only under certain conditions, please provide details on how we may recreate the same condition in order to identify the fault.

If possible, please reuse the original packaging, making sure the accessory is wrapped in heavy paper or plastic.

Alternatively, use a strong box filled with shockproof material, place enough material all around the equipment so that the unit is stable and firmly blocked inside the box.

Whilst packing, pay special care in protecting the unit's front panel.

Seal the box firmly before shipment.

Mark the box: FRAGILE HANDLE WITH CARE.

### 8.5 Cleaning

To clean the equipment use only dust-free, non-abrasive dry cloths.



**To avoid damage never use any kind of solvent, acid, or similar to clean the instrument.**

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## ***PMM 8053-OC Optical-Serial converter***

This accessory of the field probe PMM EP600/EP601/EP602/EP603 allows the fiber optic to be connected to the PC RS-232 serial port.



### **Installation**

Connect the PMM 8053-OC to a free serial port of PC; connect the fiber optic of the probe respecting the optical connector insertion key. The PMM 8053-OC is powered from the PC serial port directly.

**Table 8-1 Specifications of PMM 8053-OC**

Max allowed fiber optic length	80 m (see notes below)
RS 232 connector	9 pin DB9

### **NOTE**

For some PC models the power available at the DB9 connector may be not enough to allow the 8053-OC for driving fiber optics up to 80 m.

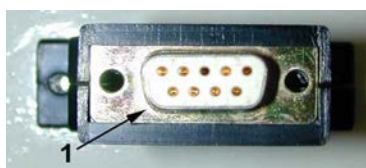
### **NOTE**

For some PC models the power available at the DB9 connector may be not enough to guarantee the correct operation of the 8053-OC. In such cases apply the 8053-OC-PS between 8053-OC and PC.



### **Front panel**

1 – fiber optic connector



### **Rear panel**

1 – RS232 DB9 female connector

**Fig. 8-1 8053-OC Panels**

### **Power supply**

The PMM 8053-OC is powered from the PC serial port directly.

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8.7

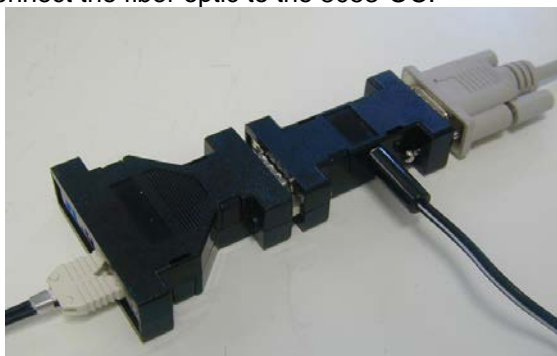
## 8053-OC-PS Power Supply



This accessory of the field probe PMM EP600/EP601/EP602/EP603 allows for providing the power supply to the 8053-OC converter whenever the PC serial port power supply is not sufficient or absent.

### Installation

Connect the 8053-OC-PS to the PC serial port (or serial cable) and to the 8053-OC. Connect the 8053-OC-PS to the mains by the AC adapter (supplied). Connect the fiber optic to the 8053-OC.



**Table 8-2 Specifications of 8053-OC-PS Power Supply**

**RS 232 Connectors**

9 pin DB9



### Front panel

DB9 M connector



### Rear panel

DB9 F connector



### Side

M connector for DC supply

**Fig. 8-2 8053-OC-PS**

### Power supply

8053-OC-PS is supplied by the 230Vac - 9Vdc Wall Adapter.

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## 8.8

### ***PMM TR-02A Tripod***



This accessory allows for standing the PMM EP600/EP601/EP602/EP603 field probe or the PMM 8053B hand held unit by means of the fixing screw. The swivel PMM 8053-SN is supplied together with the tripod.

**The PMM TR-02A has been specifically designed to prevent influencing the field measurements.**

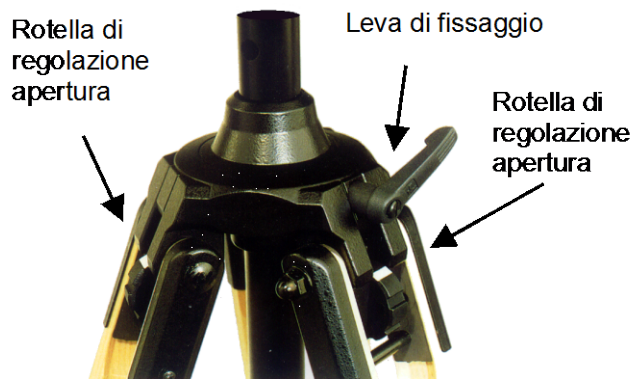
The extensible legs allow for setting the required height; the feet are designed to provide stability on most of the surfaces. The height of the central rod can be set as well.

The PMM TR-02 is supplied in a robust carrying bag.

**Table 8-3 Characteristics of PMM TR-02A**

• 3 legs of 3 extensible sections	
• Transport encumbrance:	76 x 12 x 12 cm
• Minimum height:	60 cm
• Maximum height:	180 cm
• Weight	2,8 kg
• Max load:	10 kg
• Screw connection	1/4"

Details:



The inclination of each leg can be set in three different positions:

- Fixed 20°: white mark
- Fixed 45°: red mark
- Variable: no marks visible.

The central support can be set and locked by the handle.



Fig. 8-3 TR02A

The swivel **PMM 8053-SN** can be mounted on the PMM TR-02A top.

- height: 8 cm
- weight: 160 g
- Load max: 10 kg
- Screw: ¼ "



**Fig. 8-4** adjustable swivel

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## ***PMM TT-01 Telescopic extension***

PMM TT-01 allows for extending the distance between field probe and operator or measuring instrument.

The TT-01 top is provided with the screw to fix the conical adapter. The length can be adjusted at any value between minimum and maximum.

**The PMM TT-01 is made of fibreglass and has been specifically designed to prevent influencing the field measurements.**

Table 8-4 Characteristics of TT-01	
• Diameter	32 mm
• Minimum length:	120 cm
• Maximum extension:	420 cm
• Weight	500 g



**Fig. 8-5** TT-01 Fiberglass telescopic extension with EP600/EP601/EP602/EP603 installed on the top.



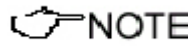
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8.10

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### ***PMM SB-10 Switching Control Box***

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PLEASE REFER TO THE RELEVANT OPERATION MANUAL

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Caro cliente

grazie per aver acquistato un prodotto NARDA! Sei in possesso di uno strumento che per molti anni ti garantirà un'alta qualità di servizio. NARDA riconosce l'importanza del Cliente come ragione di esistenza; ciascun commento e suggerimento, sottoposto all'attenzione della nostra organizzazione, è tenuto in grande considerazione. La nostra qualità è alla ricerca del miglioramento continuo. Se uno dei Suoi strumenti NARDA necessita di riparazione o calibrazione, può aiutarci a servirla più efficacemente compilando questa scheda e accludendola all'apparecchio.

Tuttavia, anche questo prodotto diventerà obsoleto. In questo caso, ti ricordiamo che lo smaltimento dell'apparecchiatura deve essere fatto in conformità con i regolamenti locali. Questo prodotto è conforme alle direttive WEEE dell'Unione Europea (2002/96/EC) ed appartiene alla categoria 9 (strumenti di controllo). Lo smaltimento, in un ambiente adeguato, può avvenire anche attraverso la restituzione del prodotto alla NARDA senza sostenere alcuna spesa. Può ottenere ulteriori informazioni contattando i venditori NARDA o visitando il nostro sito Web [www.narda-sts.it](http://www.narda-sts.it).

Dear Customer

thank you for purchasing a NARDA product! You now own a high-quality instrument that will give you many years of reliable service. NARDA recognizes the importance of the Customer as reason of existence; in this view, any comment and suggestion you would like to submit to the attention of our service organization is kept in great consideration. Moreover, we are continuously improving our quality, but we know this is a never ending process. We would be glad if our present efforts are pleasing you. Should one of your pieces of NARDA equipment need servicing you can help us serve you more effectively filling out this card and enclosing it with the product.

Nevertheless, even this product will eventually become obsolete. When that time comes, please remember that electronic equipment must be disposed of in accordance with local regulations. This product conforms to the WEEE Directive of the European Union (2002/96/EC) and belongs to Category 9 (Monitoring and Control Instruments). You can return the instrument to us free of charge for proper environment friendly disposal. You can obtain further information from your local NARDA Sales Partner or by visiting our website at [www.narda-sts.it](http://www.narda-sts.it).

☒ **Servizio richiesto:** ☒ *Service needed:*

☐ Solo taratura    ☐ Riparazione    ☐ Riparazione & Taratura    ☐ Taratura SIT    ☐ Altro:  
☐ Calibration only    ☐ Repair    ☐ Repair & Calibration    ☐ Certified Calibration    ☐ Other:

**Ditta:**

*Company:*

**Indirizzo:**

*Address:*

**Persona da contattare:**

*Technical contact person:*

**Telefono:**

*Phone n.*

**Modello:**

*Equipment model:*

**Numero di serie:**

*Serial n.*

☒ **Accessori ritornati con l'apparecchiatura:** ☐ **Nessuno**    ☐ **Cavo(i)**    ☐ **Cavo di alimentazione**    **Altro:**  
☒ *Accessories returned with unit:*    ☐ *None*    ☐ *Cable(s)*    ☐ *Power cable*    ☐ *Other:*

☒ **Sintomi o problemi osservati:** ☒ *Observed symptoms / problems:*

☒ **Guasto:** ☐ **Fisso**    ☐ **Intermittente**    **Sensibile a:** ☐ **Freddo**    ☐ **Caldo**    ☐ **Vibrazioni**    ☐ **Altro**  
☒ *Failure:* ☐ *Continuous*    ☐ *Intermittent*    *Sensitive to:* ☐ *Cold*    ☐ *Heat*    ☐ *Vibration*    ☐ *Other*

**Descrizione del guasto/condizioni di funzionamento:**

*Failure symptoms/special control settings description:*

**Se l'unità è parte di un sistema descriverne la configurazione:**

*If unit is part of system please list other interconnected equipment and system set up:*

[illegible]